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# THE NEPALI MATHEMATICAL SCIENCES REPORT

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## A Characterization of the Family of Power Distributions Through Structural Setup

T.S.K. Moothathu

### Summary

The family of power distributions is defined. The random variables such as Lognormal, Pareto, Gamma and Beta belong to this family. When the conditional distribution of  $X$  given  $XY$  has a certain structural setup,  $X$  and  $Y$  are shown to belong to the family of power distributions. The corollaries of this main result characterizes the Lognormal, Pareto, Gamma and Beta distributions.

**Key Words:** Family of Power distributions; Lognormal, Pareto (including discrete Pareto and inverse Pareto), Gamma and Beta (of first and second kind) distributions; conditional density.

### 1. Introduction

In general the marginal distributions of  $X$  and  $Y$  cannot be determined by knowing the conditional distribution of  $X$  given  $Z = U(X, Y)$ , where  $U(x, y)$  is a Borel measurable function of  $(x, y)$ . Patil and Seshadri (1964) considered  $U(X, Y) = X + Y$  (i.e.  $Z = X + Y$ ) and showed that the marginal distributions of the independent random variables  $X$  and  $Y$  (either both discrete or both continuous) are determined when the conditional distribution of  $X$  given  $Z = X + Y$  has a certain structural setup. We consider the case  $U(X, Y) = XY$  (i.e.  $Z = XY$ ). In what follows it is shown that the two non-negative independent continuous random variables  $X$  and  $Y$  belong to the family of power distributions, to be defined now, when the conditional density of  $X$  given  $XY$ ,  $c(x, z)$  has a certain structural setup.

**Definition:** If a random variable  $X$  has the probability function

$$p(x) = \begin{cases} b u(x) x^\theta, & \text{for } x \in A, b > 0, \theta \in \Omega \\ 0, & \text{elsewhere} \end{cases} \quad (1.1)$$

where  $A$  is a subset of the set of positive real numbers, and  $b$  is the normalizing factor, that is,

$$b^{-1} = \int_A u(x) x^\theta$$

where  $\int_A$  denotes the integral or summation depending upon  $X$  is continuous or discrete, and  $\Omega$  is some parameter space, which is a non-empty subset of the set of real numbers, then  $\{p(x), \theta \in \Omega\}$  is said to be a family of power distributions.

A random variable  $X$  (or its distribution) is said to belong to the family of power distributions when the probability function of  $X$  belongs to some family of power distributions.

Since, when  $X$  belongs to a family of power distributions  $\log X$  belongs to a 'linear exponential family of distributions' (Methai and Pederzoli (1977)), the family of power distributions may also be named as 'log-linear exponential family of distributions.'

Among the continuous random variables the Lognormal, Pareto, inverse Pareto (if  $X$  is Pareto,  $1/X$  is called inverse Pareto), Gamma and Beta of first and second kind belong to the family of power distributions. For, the density functions  $f_1, f_2, f_3, f_4, f_5$  and  $f_6$  of these random variables respectively are given by,

$$\begin{aligned} f_1(x) &= (x^2 \sigma^{-2} 2\pi)^{-1} \exp -(2\sigma^2)^{-1} (\log x - \mu)^2, \\ &\quad -\infty < \mu < \infty; x, \sigma > 0 \\ &= b \exp [-(2\sigma^2)^{-1} (\log x)^2] x^\theta, x > 0 \end{aligned} \quad (1.2)$$

where  $\sigma > 0$  is fixed but arbitrary,  $\theta = \mu \sigma^{-2} - 1$ ,

$$b = \{2\pi\sigma^2 \exp [(\theta\sigma + \sigma)^2]\}^{-1}, \quad -\infty < \theta < \infty.$$

$$\begin{aligned} f_2(x) &= a k^a x^{-(a+1)}, x \geq k > 0, a > 0 \\ &= b x^\theta, x \geq k > 0, \theta < -1 \end{aligned} \quad (1.3)$$

where  $k$  is fixed, but arbitrary,  $\theta = -(a+1)$  and

$$b = -(\theta + 1) k^{-(\theta + 1)}$$

$$\begin{aligned} f_3(x) &= a k^a x^{a-1} \quad 0 < x \leq k^{-1}; a, k > 0 \\ &= b x^\theta, \quad 0 < x \leq k^{-1}, \theta > -1 \end{aligned} \quad (1.4)$$

where  $k$  is fixed, but arbitrary,  $\theta = a-1$  and  $b = (1+\theta) k^{(1+\theta)}$

$$f_4(x) = b e^{-mx} x^\theta, x > 0, \theta > -1 \quad (1.5)$$

where  $m > 0$  is fixed but arbitrary and  $b = m^{(\theta+1)} (\Gamma(\theta+1))^{-1}$

$$\begin{aligned} f_5(x) &= [B(p, q)]^{-1} x^{p-1} (1-x)^{q-1}, 0 < x \leq 1; p, q > 0 \\ &= b(1-x)^{q-1} x^\theta, 0 < x \leq 1, \theta > -1 \end{aligned} \quad (1.6)$$



where  $q$  is fixed but arbitrary,  $\theta = p-1$  and  $b = [B(\theta+1, q)]^{-1}$

$$\begin{aligned} f_6(x) &= [B(p, q)]^{-1} (1+x)^{-(p+q)} x^{p-1}, \quad x, p, q > 0 \\ &= b(1+x)^{-(\theta+q+1)} x^{\theta}, \quad x > 0, \theta > -1 \end{aligned} \quad (1.7)$$

where  $q$  is fixed, but arbitrary and  $\theta = p-1$ ;  $b = [B(\theta+1, q)]^{-1}$

Reimann zeta (which is also known as discrete Pareto) variate is an example of the discrete random variable that belongs to the family of power distributions. For its probability function  $p(x)$  is given by

$$\begin{aligned} p(x) &= \left[ \sum_{r=1}^{\infty} r^{-(a+1)} \right]^{-1} x^{-(a+1)}, \quad x = 1, 2, \dots \\ &\quad a > 0 \\ &= b x^{\theta}, \quad \theta < -1, \quad x = 1, 2, \dots \end{aligned} \quad (1.8)$$

where  $\theta = -(a+1)$  and  $b = \left[ \sum_{r=1}^{\infty} r^{\theta} \right]^{-1}$

Since there are not many familiar discrete random variables which belong to the family of power distributions, we restrict our attention to continuous random variables, and establish the following characterization theorem.

## 2. A Characterization Theorem

Let the following assumptions be made about the random variables  $X$  and  $Y$ .

- (i)  $X$  and  $Y$  are non-negative independent continuous random variables.
- (ii) The density functions  $f(x)$  and  $g(y)$  of  $X$  and  $Y$  do not vanish at unity.
- (iii) The conditional density function of  $X$  given  $XY$ , denoted by  $c(x, z)$  is such that

$$\frac{c(xy, xy)}{c(x, xy)} \frac{c(1, y)}{c(y, y)} \text{ is of the form } \frac{u(xy)}{u(x) u(y)}$$

where  $u(\cdot)$  is an arbitrary non-negative function.

The following theorem can now be established to characterize several families of power distributions.

Theorem: Under the assumptions (i) - (iii)

$$f(x) = f(1) u(x) x^{\theta}$$

where  $\theta$  is an arbitrary constant and  $f(1)$  a suitable normalizer which makes  $f(x)$  a density function,

$$g(y) = g(1) k(y) y^{\theta} \quad \text{where}$$

$$k(y) = u(y) c(1,y)/y c(y,y)$$

and  $g(1)$  is the corresponding normalizer for  $g(y)$ . Further if

$$(iv) \quad B = \{x: u(x) > 0\} = \{y: k(y) > 0\} \quad \text{and}$$

$$c(y,y) = y^{-1} c(1,y), \quad y \in B$$

then  $X$  and  $Y$  are identifiably distributed.

Proof: We have

$$c(x,xy) = \frac{f(x) g(y)}{x r(xy)}$$

$$\text{where } r(z) = \int x^{-1} f(x) g(z/x) dx.$$

Hence

$$f(x) g(y) = x r(xy) c(x,xy) \quad (2.1)$$

Put  $y = 1$  in (2.1) and change  $x$  to  $xy$  to obtain

$$f(xy) g(1) = xy r(xy) c(xy,xy) \quad (2.2)$$

Thus

$$\frac{f(xy) g(1)}{f(x) g(y)} = \frac{y c(xy, xy)}{c(x, xy)} \quad (2.3)$$

Setting  $x = 1$  in (2.3) yields

$$\frac{f(y) g(1)}{f(1) g(y)} = \frac{y c(y,y)}{c(1,y)} \quad (2.4)$$

From (2.3) and (2.4) it is clear that

$$\frac{f(xy) f(1)}{f(x) f(y)} = \frac{c(xy,xy) c(1,y)}{c(x,xy) c(y,y)}$$

and by assumption (iii),

$$\frac{f(xy) f(1)}{f(x) f(y)} = \frac{u(xy)}{u(x) u(y)} \quad (2.5)$$



The transformation  $\phi(x) = \frac{f(x)}{f(1) u(x)}$  reduces (2.5) to a Cauchy functional equation  $\phi(xy) = \phi(x) \phi(y)$  whose solution is  $x^\theta$  for some constant  $\theta$ . Thus

$$f(x) = f(1) u(x) x^\theta,$$

$f(1)$  being a suitable normalizer that makes  $f(x)$  a density function. And from (2.4)

$$f(y) = g(1) k(y) y^\theta$$

where  $k(y) = u(y) c(1, y)/y c(y, y)$  and  $g(1)$  is the corresponding normalizer of  $g(y)$ .

Further under the assumption (iv), we have

$$k(y) = u(y), \quad y \in B \text{ and the requirement}$$

$$1 = \int_B f(x) dx = \int_B g(y) dy \text{ yields}$$

$$f(x) = g(x), \quad x \in B.$$

Thus  $X$  and  $Y$  are identically distributed.

Notice that once the function  $c(x, z)$  is specified the domain of the functions  $u(x)$  and  $k(y)$  - the sets  $\{x : u(x) > 0\}$  and  $\{y : k(y) > 0\}$  - can be determined since the transformation from  $(x, z)$  to  $(x, y)$  where  $z = xy$ , is one-to-one.

The Beta distribution, with density function (1.6) though belongs to the family of power distributions, does not come under the purview of the above theorem, since its density function vanishes at unity. In what follows the random variables  $X$  and  $Y$  are assumed to satisfy assumptions (i) and (ii).

Corollary 1: Let

$$c(x, z) = \text{const. } x^{-1} \exp \left[ -(2 \sigma_1^2)^{-1} (\log x - \frac{1}{2} \log z)^2 \right], \quad x, z > 0.$$

Then

$$u(x) = \exp \left[ -(2 \sigma_1^2)^{-1} (\log x)^2 \right], \quad x > 0$$

$$k(y) = \exp \left[ -(2 \sigma_1^2)^{-1} (\log y)^2 \right], \quad y > 0$$

where  $\sigma_1^2 = 2 \sigma^2$ . Thus  $X$  and  $Y$  are identically distributed and the common density function  $f(\cdot)$  is given by

$$f(x) = f(1) \exp \left[ -(2 \sigma_1^2)^{-1} (\log x)^2 \right] x^\theta, \quad x > 0, \quad -\infty < \theta < \infty$$

Corollary 2: Let

$$c(x, z) = [x \log (z/k)]^{-1}, \quad k \leq x \leq z < \infty, \quad 0 < k \leq 1, \quad z \neq 1$$

Then

$$u(x) = 1, \quad x \geq k$$

$$k(y) = 1, \quad y \geq 1$$

$$\text{Thus } f(x) = f(1) x^\theta, \quad x \geq k \quad \theta < -1$$

$$g(y) = g(1) y^\theta, \quad y \geq 1$$

Thus X and Y are distributed (identically when  $k = 1$ ) as Pareto.

Corollary 3: Let

$$c(x, z) = [x \log (k/z)]^{-1}, \quad 0 < z \leq x \leq k, \quad z \neq 1, \quad k \geq 1$$

Then

$$u(x) = 1, \quad 0 < x \leq k$$

$$k(y) = 1, \quad 0 < y \leq 1$$

Thus

$$f(x) = f(1) x^\theta, \quad 0 < x \leq k \quad k \geq 1, \quad \theta > -1$$

$$g(y) = g(1) y^\theta, \quad 0 < y \leq 1$$

Thus X and Y are distributed (identically when  $k = 1$ ) as inverse Pareto.

Corollary 4: Let

$$c(x, z) = \left\{ x s_1(z) \exp [m(x+z/x)] \right\}^{-1}, \quad x, z, m > 0$$

$$\text{where } s_1(z) = \int_0^\infty x^{-1} \exp [-m(x+z/x)] dx$$

Then

$$u(x) = \exp [-m(x+1)], \quad x > 0$$

$$k(y) = \exp [-m(y+1)], \quad y > 0$$

Thus X and Y are identically distributed as Gamma and the common density function  $f(\cdot)$  is given by, after some adjustments,

$$f(x) = f(1) e^{-mx} x^{\theta}, \quad x > 0, \quad \theta > -1$$

Corollary 5: Let

$$c(x, z) = [x s_2(z)]^{-1} z^{m-1} [(1+x)(1+z/x)]^{-(m+n)},$$

$$x, z, m, n > 0.$$

where

$$s_2(z) = \int_0^{\infty} x^{-1} z^{m-1} [(1+x)(1+z/x)]^{-(m+n)} dx$$

Then

$$u(x) = \left(\frac{1+x}{2}\right)^{-(m+n)}, \quad x > 0$$

$$k(y) = \left(\frac{1+y}{2}\right)^{-(m+n)}, \quad y > 0$$

Thus X and Y are identically distributed as Beta (of second kind) and the common density function  $f(\cdot)$  is given by,

$$f(x) = f(1) (1+x)^{-(m+n)} x^{\theta}, \quad x > 0; \quad \theta < m+n-1$$

Corollary 6: Let

$$c(x, z) = m \exp [m(1-x)], \quad x \geq z > 0; \quad m > 0,$$

Then

$$u(x) = \exp [m(1-x)], \quad x > 0$$

$$k(y) = y^{-1}, \quad 0 < y \leq 1$$

Thus

$$f(x) = f(1) \exp (-mx) x^{\theta}, \quad x > 0$$

$$g(y) = g(1) y^{\theta-1}, \quad 0 < y \leq 1$$

$$\theta > 0$$

Thus X is distributed as Gamma and Y is distributed as inverse Pareto.

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## Childhood Mortality Estimation for Hilly Region of Nepal

Mrs. Ganga Shrestha

The present paper deals with estimating the childhood mortality on the basis of the information on total number of children ever born and children surviving for different age groups of mothers. The estimation is based on the data from Nepal Fertility Survey which was conducted in the international level in the year 1976 from April to June.

### Introduction

The main objective of the World Fertility Survey was to study human fertility and the factors which affect it in as many countries of the world as are willing to participate. In addition to the division of Nepal into four development regions, the country is divided into three geographic areas, the mountains, the hills and the Terai. The mountains range in altitude from 16000 ft. to 29028 ft. including 35% of the total land area and 10% of the total population of the country.

The hill region range in altitude from above 1000 ft. to about 16000 ft. including Kathmandu Valley and Pokhara. This area includes 44% of the total area and includes more than 52% of the total population. The Terai area range from about 200 ft. to 1000 ft. above sea level and includes about 1/5th of the total land area and little over 37% of the total population.

Our study is based on the data for Hill region only.

It is a well known fact that the level of infant mortality and childhood mortality depends on the proportion of children surviving to the mothers of different age groups. Thus the census reports in which data on surviving children are included often contain comments that variations within the enumerated population in proportions surviving can be considered as an index of differential mortality.

William Brass has greatly increased the usefulness of data of this sort by developing a method of translating proportions surviving and proportions dead among the children ever born to women in different age groups into conventional measure of mortality. His technique makes it possible under certain circumstances to estimate the proportion of children who survive to age 1,2,3,5,10,15,20, ... etc. from the proportion as surviving among children ever born to women of age groups 15-19, 20-24, 25-29, ... 60-64.

### Application

The data from World Fertility Survey, Nepal for hill region was used to compute the proportion of children dying to mothers of the above age-groups as described in Table 1.



Table 1  
Childhood Mortality Estimation

Age group	Proportion ever married	No. ever married	Total No. of women	Children ever born (CEB)	Children surviving	Proportion dying	Mean CEB $P_i$
15-19	.6269	361	575.85	105	91	.1333	.1823
20-24	.9397	583	620.41	835	671	.1964	1.3459
25-29	.9823	582	592.49	1628	1275	.2168	2.7477
30-34	.988	429	434.21	1745	1353	.2246	4.0188
35-39				1845	1356	.2650	
				2202	1573	.2856	
				1600	1158	.2763	

Source:- Data from Brall 7125178 Jot 0715.

It has been seen that the proportion dead for a given age group of mother ( $D_i$ ) depends on the length of time since the children were born and may be equated to the probability of dying between birth and some age  $r$  denoted by  $q(r)$ ,  $r$  will depend on the differences between the ages of mother at the time of the survey and those at which the children were born that is on how early the child bearing starts. It will also be affected by the way fertility changes with age of woman and the pattern of mortality in childhood. Since the effect of these are subsidiary only the estimation is based on some knowledge of the location of the fertility distribution. This was done by the numerical calculation of the values of  $r$  for a fixed standard pattern of mortality and a model fertility distribution of a simple form which varied only with the mean age of child bearing. It can be assumed that the proportion of children dying before their first birthday is close to the proportion dead among those ever born to women in the age group 15-19, the proportion dying before their second birth day close to the proportion dead among the children ever born to women 20-24, the proportion dying before their third birth day close to the proportion dead among the children ever born to women 25-29, the proportion dying before their fifth birth close to the proportion dead among the children ever born to women 30-34, before the tenth birth day to the proportion dead among the children ever born to women 35-39 and so on.

To compute  $q(r)$  that is the proportion of children born alive who die by age  $r$ , the proportion of children dead  $D_i$  were multiplied by their corresponding multiplying factors where  $D_i$  is given by

$$D_i = \frac{\text{CEB-CS}}{\text{CEB}}$$

The result is presented in Table II. In order to select the right series of the multiplying factors by age group for deriving  $q(r)$  from the observed  $D_i$  an estimate of the location of child bearing is needed.



In this case the ratio  $P_2/P_3$  is considered a suitable choice of a location parameter, where  $P_2$  and  $P_3$  are the mean children ever born in the age groups 20-24 and 25-29 respectively, since  $P_1$  the mean children ever born in the age group 15-19 is supposed to be sensitive to age reporting errors at the start of child bearing and also sample fluctuation due to the relatively small number of births to women in that age group.  $P_2/P_3$  is particularly satisfactory for the estimates of  $q(2)$ ,  $q(3)$  and  $q(5)$ . Hence the multiplying factors are selected corresponding to  $P_2/P_3$  which was .490 in this case.

Table II  
Estimation of Childhood Mortality Nepal WFS 1976

Age group	Multiply- ing factor K	Proportion dying $D_i$	Estimated		$Y_s(r)^*$	Graduated	
			$q(P)$ $KD_i$	$Y(P)$ logit ( $1-q(r)$ )		$Y(r)$	$q(r)$
15-19	0.977	.1333	.1302	.9496	.8670	.8861	.1453
20-24	1.101	.1964	.1984	.6982	.7152	.7183	.1921
25-29	0.994	.2168	.2155	.6420	.6552	.6519	.2135
30-34	1.002	.2246	.2250	.6184	.6015	.5925	.2342
35-39	1.011	.2650	.2679	.5027	.5498	.5354	.2553
40-44	0.988	.2856	.2822	.4668	.5131	.4948	.2710
45-59	0.986	.2763	.2724	.4912	.4551	.4306	.2971

\*Logit of the general standard life table.

It has been found that the probability of dying from birth to age one is estimated as .1333 that is the infant mortality is 133 per thousand which seems to be quite smaller than what it should be. Usually in developing countries it has been supposed that the estimates of  $q(r)$  derived in this way may be affected by some errors. It seems that children who die very young may be omitted from the records, also the absence of the children of mother who died in child birth may be missed from reporting and thus will lower the rates since these births have a smaller chance of surviving. Such graduation also helps in reducing sampling errors when the data are from small surveys.

In the graduation method first of all the  $q(r)$  values are transferred to logit values given by

$$Y(x) = 1/2 \log_e \frac{q(x)}{1-q(x)}$$

In the logit model system

$$Y(x) = \alpha + \beta Y_s(x)$$

which is assumed to be linear. Here  $Y_s(x)$  is the logit taken from the standard life table and  $\alpha$  and  $\beta$  are constants. The average of the three

estimated logits in age group 20-24, 25-29, 30-34 and the corresponding average of the same three logits from the standard values were computed. Also the average of the logits of the later three age groups for the estimated and standard values were computed. These values were respectively found to be .6542, .6573, .4869 and .5060. The parameters  $\alpha$  and  $\beta$  were computed by solving the two equations

$$.6542 = \alpha + .6573 \beta$$

$$.4869 = \alpha + .5060 \beta$$

which were obtained as

$$\alpha = -.0726, \beta = 1.1058$$

The graduated logit is obtained by the relation

$$\text{logit } 1-q(r) = + \log 1-q_s(r)$$

and the graduated  $q(r)$  is given by

$$q(r) = \frac{1}{1 + e^{2 \text{ logit } 1-q(r)}}$$

The graduated estimates are also presented in table number II. The graduated value of  $q(1)$  i.e. .1453 seem to be better than the estimated  $q(1)$  which is .1333. In the Nepal Fertility Survey Report the infant deaths in the years 2028, 2029 and 2030 and dividing by the total number of live births during that period was 152 per thousand which is considered to be small than our actual infant mortality. The infant mortality from Demographic sample survey 1976 is 52.79 per thousand for urban Nepal and 136.10 per thousand for rural Nepal which seem to be still smaller and more unreliable than the former one.

The estimate of  $q(1)$  obtained in this study may not be reliable because of the difficulty of locating fertility at the beginning of reproduction precisely and the sampling fluctuations from small numbers. The estimate may be more representative if  $q(2)$  may be considered as  $q(1)$  which are .1984 as estimated value and .1921 as the graduated value so that the infant mortality will come as 198 per thousand and 192 per thousand in the two cases.

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## On a Distributional Poisson Transform

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### 1. Abstract

A complex inversion formula is obtained for the Poisson Transform and is extended to generalized functions interpreting convergence in the weak distributional sense.

### Introduction

Let  $f(y)$  belong to  $L$  in  $(-R < y < R)$  for every positive  $R$  and be such that the integral

$$(1.1) \quad F(x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1}{1 + (x-y)^2} f(y) dy$$

converges for  $|\operatorname{Im} x| < 1$ .

The inversion operator for (1.1) as defined by Pollard, H. [2] is as follows:

$$(1.2) \quad T_t(F(x)) = \left(\frac{\sin tD}{D}\right) \hat{F}(x) + (\cos tD)F(x)$$

where

$\hat{F}$  is defined by

$$(1.3) \quad \hat{F}(x) = -\frac{1}{\pi} \int_0^{\infty} u^{-2} [F(x+u) + F(x-u) - 2F(x)] du.$$

Pollard, H. [2] has shown that

$$\lim_{t \rightarrow 1^-} T_t(F(x)) = f(x).$$

The purpose of the present paper is to find out a complex inversion formula for (1.1) and to extend it to generalized functions in the weak distributional sense.

### 2. Notation and Terminology

$R$  denotes the real one-dimensional Euclidean space. A function is said to be smooth if its derivatives of all orders are continuous at all points of its domain.  $\langle f, \phi \rangle$  denotes the number assigned to some element  $\phi$  in a certain testing function space by a member of the dual space.  $D$  is the space of smooth functions on  $R$  having compact support.  $D'$  is the dual space of  $D$ .

### 3. Testing Function Space $H_{n,\alpha}$ .

An infinitely differentiable complex valued function  $\phi(y)$  defined over  $I(-\infty, \infty)$  satisfying the relation

$$\gamma_n(\phi(y)) = \gamma_{n,\alpha}(\phi) = \sup_{-\infty < y < \infty} |(1+y^2)^{\alpha/2} y^n D^n \phi(y)| < \infty$$

belongs to  $H_{n,\alpha}$  for any fixed  $n$  where  $n$  assumes the values  $0, 1, 2, 3, \dots$  and  $\alpha \leq 1$ .  $\gamma_0$  is a norm and hence the collection of semi-norms is separating [4, p. 8]. The topology of  $H_{n,\alpha}$  is generated by the collection of semi-norms  $\{\gamma_n\}_{n=0}^{\infty}$ . A sequence  $\{\phi_\nu\}_{\nu=1}^{\infty}$  where each  $\phi_\nu \in H_{n,\alpha}$  is said to converge in  $H_{n,\alpha}$  to the limit  $\phi$  in  $H_{n,\alpha}$  if  $\gamma_n(\phi_\nu - \phi) \rightarrow 0$  as  $\nu \rightarrow \infty$  for each  $n = 0, 1, 2, \dots$ . A sequence  $\{\phi_\nu\}_{\nu=1}^{\infty}$  is said to be a Cauchy sequence if  $\gamma_n(\phi_\nu - \phi_\mu) \rightarrow 0$  as  $\nu$  and  $\mu$  both tend to infinity independently of each other.

#### Lemma 3.1

For any  $\alpha \leq 1$  and for any complex  $x$  such that  $|\operatorname{Im} x| < 1$ , ( $\operatorname{Re} x = \sigma$ ,  $\operatorname{Im} x = \tau$ )

$$\phi(y) = \frac{1}{\pi} \frac{1}{1 + (x-y)^2} \text{ belongs to } H_{n,\alpha}.$$

Proof:-

$$\begin{aligned} \gamma_{n,\alpha}(\phi) &= \sup_{-\infty < y < \infty} |(1+y^2)^{\alpha/2} y^n D^n \phi(y)| \\ &= \sup_{-\infty < y < \infty} \left| (-1)^n n! (1+y^2)^{\alpha/2} y^n \frac{\sin \left\{ (n+1) \arctan \frac{1}{x-y} \right\}}{[1 + (x-y)^2]^{1/2} (n+1)} \right| \\ &\leq \sup_{-\infty < y < \infty} \left( \frac{1+y^2}{y^2} \right)^{\alpha/2} |y|^{\alpha-1} \frac{1}{\left\{ \frac{1-y^2}{y^2} + (\sigma/\tau-1)^2 \right\}^{1/2} (n+1)} \end{aligned}$$

which is bounded for all values of  $y$  for  $\alpha \leq 1$ . This completes the proof of the lemma.

#### Lemma 3.2

For an arbitrary element  $f(t) \in H_{n,\alpha}^1$  and  $\alpha \leq 1$ , let



$$F(x) = \left\langle f(t), \frac{1}{\pi} \frac{1}{1+(x-y)^2} \right\rangle$$

for any  $x$  in the complex plane for which  $|\operatorname{Im} x| < 1$ , then for  $k = 0, 1, 2, \dots$

$$F^{(k)}(x) = \left\langle f(t), \left(\partial/\partial x\right)^k \left\{ \frac{1}{\pi} \frac{1}{1+(x-y)^2} \right\} \right\rangle$$

The proof of this lemma follows from Bajracharya, B.C. [17].

#### 4. Complex Inversion Formula

If  $F(x)$  and  $\widehat{F}(x)$ , defined by (1.1) and (1.3), converge, then

$$\lim_{t \rightarrow 1} \left[ 2^{-1} \{ F(x+it) + F(x-it) \} + (2iD)^{-1} \{ \widehat{F}(x+it) - \widehat{F}(x-it) \} \right] = f(x)$$

where  $x$  is a real variable.

Proof:

Since

$$F(x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1}{1+(x-y)^2} f(y) dy,$$

so

$$\begin{aligned} 2^{-1} [F(x+it) + F(x-it)] &= (2\pi)^{-1} \int_{-\infty}^{\infty} \left\{ \frac{1}{1+(x-y+it)^2} + \frac{1}{1+(x-y-it)^2} \right\} f(y) dy \\ (4.1) \quad &= \pi^{-1} \int_{-\infty}^{\infty} \frac{1-t^2 + (x-y)^2}{1+2(x-y)^2 - 2t^2 + (x-y)^4 + 2t^2(x-y)^2 + t^4} f(y) dy \end{aligned}$$

Also since

$$\begin{aligned} 1 + 2(x-y)^2 - 2t^2 + (x-y)^4 + 2t^2(x-y)^2 + t^4 \\ = \{ (1+t)^2 + (x-y)^2 \} \{ (1-t)^2 + (x-y)^2 \}, \end{aligned}$$

setting  $1+t = a$ ,  $1-t = b$  and  $x-y = z$  in

$$\frac{1-t^2 + (x-y)^2}{\{ (1+t)^2 + (x-y)^2 \} \{ (1-t)^2 + (x-y)^2 \}}$$



$$\frac{ab+z^2}{(a^2+z^2)(b^2+z^2)} = \frac{Az+B}{a^2+z^2} + \frac{Cz+D}{b^2+z^2}$$

where A, B, C, D are constants to be determined.

Therefore,

$$z^2 + ab = z^3 (A+C) + z^2 (B+D) + z(Ab^2 + Ca^2) + (Bb^2 + Da^2)$$

Equating the coefficients of like terms,

$$(4.2) \quad A+C=0$$

$$(4.3) \quad B+D=1$$

$$(4.4) \quad Ab^2 + Ca^2 = 0$$

$$(4.5) \quad Bb^2 + Da^2 = ab$$

Solving the above four equations we have,

$$A=C=0 \text{ and } B = \frac{1+t}{2}, \quad D = \frac{1-t}{2}$$

Thus,

$$(4.6) \quad 2^{-1} [F(x+it) + F(x-it)] \\ = (2\pi)^{-1} \int_{-\infty}^{\infty} \left[ \frac{1-t}{(1-t)^2 + (x-y)^2} + \frac{1+t}{(1+t)^2 + (x-y)^2} \right] f(y) dy$$

Next, using Pollard, H. [2]

$$F(x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1 - (x-y)^2}{t^2 + (x-y)^2} f(y) dy$$

and a process similar to the above case we obtain

$$(4.7) \quad (2iD)^{-1} [\hat{F}(x+it) - \hat{F}(x-it)] \\ = (2\pi)^{-1} \int_{-\infty}^{\infty} \left[ \frac{1-t}{(1-t)^2 + (x-y)^2} - \frac{1+t}{(1+t)^2 + (x-y)^2} \right] f(y) dy$$

Now in view of (4.6) and (4.7)

$$\lim_{t \rightarrow 1-} \left[ 2^{-1} \{F(x+it) + F(x-it)\} + (2iD)^{-1} \{\hat{F}(x+it) - \hat{F}(x-it)\} \right]$$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1-t}{(1-t)^2 + (x-y)^2} f(y) dy. \text{ as } t \rightarrow 1-$$

$\rightarrow f(x)$  as  $t \rightarrow 1-$  which has been shown by Pollard, H. [2]

### 5. Distributional Complex Inversion for the Poisson Transform

#### Theorem 5.1

If  $f(y) \in H'_{n,\alpha}$  and  $F(x)$  be the Poisson transform of  $f(y)$ , then for an arbitrary element  $\phi(x) \in D(I)$ , we have

$$\begin{aligned} & \left\langle \left[ 2^{-1} \{F(x+it) + F(x-it)\} + (2iD)^{-1} \{ \hat{F}(x+it) - \hat{F}(x-it) \} \right], \phi(x) \right\rangle \\ & \rightarrow \langle f(y), \phi(y) \rangle \text{ as } t \rightarrow 1- \end{aligned}$$

Proof: Since

$$F(x) = \left\langle f(y), \frac{1}{\pi} \frac{1}{1 + (x-y)^2} \right\rangle,$$

the theorem will be proved if the steps in the following manipulations are justified.

$$\begin{aligned} & \left\langle \left[ 2^{-1} \{F(x+it) + F(x-it)\} + (2iD)^{-1} \{ \hat{F}(x+it) - \hat{F}(x-it) \} \right], \phi(x) \right\rangle \\ (5.1) \quad & = \left\langle \left\langle f(y), \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2} \right\rangle, \phi(x) \right\rangle \end{aligned}$$

$$\begin{aligned} (5.2) \quad & = \left\langle f(y), \left\langle \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2}, \phi(x) \right\rangle \right\rangle \\ & \rightarrow \langle f(y), \phi(y) \rangle \text{ as } t \rightarrow 1-. \end{aligned}$$

Some simple calculations justify the relation (5.1). The equality of relation (5.1) to the relation (5.2) is justified by a process very similar to Zemanian [3, p. 237]

Now, to complete the proof, it suffices to show that

$$\left\langle \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2}, \phi(x) \right\rangle \rightarrow \phi(y) \text{ as } t \rightarrow 1-$$

Therefore,

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$$\begin{aligned} & (1+y^2)^{-1/2} y^n D_y^n \left[ \left\langle \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2}, \phi(x) \right\rangle - \phi(y) \right] \\ &= (1+y^2)^{-1/2} y^n \left[ \left\langle (-D_x)^n \left\{ \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2} \right\}, \phi(x) \right\rangle - D_y^n \phi(y) \right] \end{aligned}$$

Integration by parts leads to

$$\begin{aligned} & (1+y^2)^{-1/2} y^n \left[ \left\langle \frac{1}{\pi} \frac{1-t}{(1-t)^2 + (x-y)^2}, D_x^n \phi(x) \right\rangle - D_y^n \phi(y) \right] \\ &= (1+y^2)^{-1/2} y^n \left[ \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1-t}{(1-t)^2 + (x-y)^2} (D_x^n \phi(x)) dx - D_y^n \phi(y) \right] \\ (5.3) \quad &= \frac{(1+y^2)^{-1/2} y^n}{\pi} \int_{-\infty}^{\infty} \frac{1-t}{(1-t)^2 + (x-y)^2} (\phi^n(x) - \phi^n(y)) dx \end{aligned}$$

where  $\phi^n(x) \triangleq D_x^n \phi(x)$  and

$$\frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1-t}{(1-t)^2 + (x-y)^2} dx = 1$$

The right hand side of (5.3) tends to zero as  $t \rightarrow 1^-$  which has already been shown in Bajracharya, B.C. [1].

This completes the proof of the theorem.

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## A Characterization of Hypodivergence Measure

Parvinder Kaur

### Summary

The hypodivergence measure between two discrete distribution is characterized in this paper with the help of a functional inequality.

### 1. Introduction

Let  $P = (p_1, p_2, \dots, p_n)$   $Q = (q_1, q_2, \dots, q_n)$ ,  $p_i, q_i \geq 0$  with  $\sum_{i=1}^n p_i = \sum_{i=1}^n q_i = 1$  be two finite discrete probability distributions. Then the directed divergence defined by Kullback (1959) between two distributions  $P$  and  $Q$  is

$$I_n(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = \sum_{i=1}^n p_i \log \frac{p_i}{q_i} \quad (1.1)$$

where the convention followed is that whenever a  $q_i = 0$  the corresponding  $p_i = 0$  and that  $0 \log \frac{0}{0} = 0$ . This convention however, is not always very appealing.

Carlo Fereeri [1] has defined a hypodivergence measure between two probability distributions  $P$  and  $Q$  as

$$J_\lambda(P:Q) = \frac{1}{\lambda} \sum_{i=1}^n (1 + \lambda p_i) \log \frac{1 + \lambda p_i}{1 + \lambda q_i} \quad (1.2)$$

$$\lambda > 0, \quad 0 \leq J_\lambda(P:Q) \leq \log(1 + \lambda)$$

The above hypodivergence measure (1.2) reduces to (1.1) as  $\lambda \rightarrow \infty$  while for finite  $\lambda$  it permits to overcome the difficulty in defining (1.1) that (1.1) is defined only for  $q_i > 0$ . Thus, the convention followed in defining (1.1) is totally removed in defining (1.2).

The above quantity (1.2) is characterized in the next section with the help of the functional inequality

$$\sum_{i=1}^n (1 + \lambda p_i) [f(p_i) - f(q_i)] \geq 0 \quad (1.3)$$

## 2. Characterization

Theorem: If a function  $H_\lambda(P;Q)$  satisfies the following postulates

$$A_1 : H_\lambda(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = \sum_{i=1}^n (1 + \lambda p_i) [f(p_i) - f(q_i)]$$

$$A_2 : H_\lambda(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) \geq 0$$

and

$$A_3 : H_2(1, 0; 0, 1) = \log(1 + \lambda)$$

then

$$H_\lambda(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = J_\lambda(P;Q)$$

$$\frac{1}{\lambda} \sum_{i=1}^n (1 + \lambda p_i) \log \frac{1 + \lambda p_i}{1 + \lambda q_i}, \lambda > 0$$

Before proving the theorem we shall first find the solution of the functional inequality (1.3) in the following lemma.

Lemma: Every solution of functional inequality (1.3) is differentiable everywhere in  $(0,1)$  and the solutions are given by

$$f(x) = \frac{a}{\lambda} \log(1 + \lambda x)$$

where  $a$  is any constant.

Proof of Lemma: Let us first show that  $f$  is monotone increasing in  $[0,1]$

In the inequality (1.3) taking  $p_3 = q_3, p_4 = q_4, \dots, p_n = q_n$ , we have

$$(1 + \lambda p_1) [f(p_1) - f(q_1)] + (1 + \lambda p_2) [f(p_2) - f(q_2)] \geq 0 \quad (2.1)$$

with  $p_1 + p_2 = q_1 + q_2 < 1$

or

$$\frac{1 + \lambda p_1}{1 + \lambda p_2} [f(p_1) - f(q_1)] + [f(p_2) - f(q_2)] \geq 0 \quad (2.2)$$

Interchanging  $p_1$  and  $q_1$  and  $p_2$  and  $q_2$  in (2.2), we get

$$\frac{1+\lambda q_1}{1+\lambda q_2} [f(q_1) - f(p_1)] + [f(q_2) - f(p_2)] \geq 0 \quad (2.3)$$

Adding (2.2) and (2.3) we have

$$\frac{1+\lambda p_1}{1+\lambda p_2} - \frac{1+\lambda q_1}{1+\lambda q_2} [f(p_1) - f(q_1)] \geq 0$$

Now let  $q_1 > p_1$ ,  $q_2 < p_2$

so that

$$\frac{1+\lambda p_1}{1+\lambda p_2} < \frac{1+\lambda q_1}{1+\lambda q_2}$$

$$\text{implying } f(p_1) \leq f(q_1) \text{ for } p_1 < q_1 \quad (2.4)$$

which shows that  $f$  is monotone increasing in  $[0, 1]$

Now in order to prove that  $f$  is differentiable every where in  $(0,1)$  let us prove that at all those points  $p \in (0,1)$  at which  $f$  is differentiable

$$(1+\lambda p) f'(p) = a \geq 0 \quad (2.5)$$

holds

Since  $f$  is monotone increasing in  $(0,1)$ , it is differentiable almost every where in  $(0,1)$  (cf. Natanson 1964, p. 211). The inequality (2.1) may be written as

$$(1+\lambda p_1) [f(p_1) - f(q_1)] \geq (1+\lambda p_2) [f(q_2) - f(p_2)] \quad (2.6)$$

Putting  $q_1 = p_1 + \delta$ ,  $q_2 = p_2 - \delta$ ,  $\delta > 0$  in (2.6) and dividing both sides by  $\delta$ , we have

$$(1+\lambda p_1) \left[ \frac{f(p_1) - f(p_1 + \delta)}{\delta} \right] \geq (1+\lambda p_2) \left[ \frac{f(p_2 - \delta) - f(p_2)}{\delta} \right] \quad (2.7)$$

with  $0 < \delta < p_2 < 1-p_1$

Let  $p_1$  and  $p_2$  be the points where  $f$  is differentiable. Taking  $\delta \rightarrow 0$  in (2.7) and using symmetry in  $p_1$  and  $p_2$ , we get

$$(1+\lambda p) f'(p) = a \quad (2.8)$$



where  $a$  is some constant.

Since  $f$  is monotone increasing in  $(0,1)$ ,  $f'(p) \geq 0$  giving  $a \geq 0$ .

Now let  $p$  be an arbitrary point and let  $D^+$ ,  $D^-$ ,  $D_+$ ,  $D_-$  be the four Dini-derivatives at  $p$ . Let  $p_1$  be a point at which  $f$  is differentiable.

In (2.7) with  $p_2 = p$ , we obtain on taking  $\inf \delta \rightarrow 0$ , from (2.7) and (2.8)

$$a \leq (1 + \lambda p) D_- f(p) \quad (2.9)$$

Again taking  $p_1 = p$  in (2.7) and supposing that  $f$  is differentiable at  $p_2$  and taking  $\sup \delta \rightarrow 0$ , we get

$$(1 + \lambda p) D^+ f(p) \leq a \quad (2.10)$$

Taking  $p_1 = q_1 + \delta$ ,  $p_2 = q_2 - \delta$ ,  $\delta > 0$  in (2.6), we have on division by

$$(1 + \lambda(q_1 + \delta)) \left[ \frac{f(q_1 + \delta) - f(q_1)}{\delta} \right] \geq (1 + \lambda(q_2 - \delta)) \left[ \frac{f(q_2) - f(q_2 - \delta)}{\delta} \right] \quad (2.11)$$

with  $0 < \delta < q_2 < 1 - q_1$

Now assuming  $f$  to be differentiable at  $q_1$  and taking  $q_2 = p$ ,

then taking  $\sup \delta \rightarrow 0$ , (2.11) gives

$$(1 + \lambda p) D^- f(p) \leq a \quad (2.12)$$

Lastly, taking  $q_1 = p$  and  $f$  to be differentiable at  $q_2$  in (2.11) and taking  $\inf \delta \rightarrow 0$

$$(1 + \lambda p) D_+ f(p) \geq a \quad (2.13)$$

Hence for an arbitrary  $p \in (0,1)$  we have from (2.9), (2.10), (2.12) and (2.13) that

$$D_- f = D^- f = D^+ f = D_+ f$$

Therefore,  $f$  is differentiable every where in  $(0,1)$  and we have

$$f'(p) = \frac{a}{a + \lambda p}$$

giving

$$f(p) = \frac{a}{\lambda} \log(1 + \lambda p) \quad (2.14)$$

This completes the proof of lemma.

Proof of theorem

Using postulates  $A_1$  and  $A_2$

$$H_{\lambda}(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = \sum_{i=1}^n (1 + \lambda p_i) [\bar{f}(p_i) - f(q_i)] \geq 0 \quad (2.15)$$

From (2.14) and (2.15)

$$H_{\lambda}(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = \sum_{i=1}^n (1 + \lambda p_i) \frac{a}{\lambda} \log \frac{1 + \lambda p_i}{1 + \lambda q_i} \quad (2.16)$$

Using postulate  $A_3$ , we get

$$a = 1$$

Hence

$$H_{\lambda}(p_1, p_2, \dots, p_n; q_1, q_2, \dots, q_n) = \frac{1}{\lambda} \sum_{i=1}^n (1 + \lambda p_i) \log \frac{1 + \lambda p_i}{1 + \lambda q_i} = J_{\lambda}(P:Q)$$

This proves the theorem.

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## Hydromagnetic Pulsating Flow of Visco-Elastic Fluid Between Two Parallel Porous Surfaces

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### Abstract

The exact solution is obtained for unsteady flow of an incompressible visco-elastic (Revin-Ericksen model) conducting fluid between two non-conducting parallel porous surfaces with oscillating pressure gradient in time when there is uniform suction and injection on both the surfaces in the presence of uniform transverse magnetic field.

### 1. Introduction

The exact solution for unsteady flow of an incompressible viscous fluid between two parallel surfaces with oscillating pressure gradient in time has been obtained in [1]. The exact solution for unsteady flow of an incompressible viscous conducting fluid between two non-conducting parallel surfaces with oscillating pressure gradient in time has been obtained by the author [3] in the presence of uniform transverse magnetic field. This analysis has been extended by the author [4] to visco-elastic (Revin-Ericksen model) fluid. The exact solution for unsteady flow of an incompressible viscous conducting fluid between two non-conducting parallel porous surfaces with oscillating pressure gradient in time has also been obtained by the author [5] when there is an equal uniform suction and injection on both the surfaces in the presence of uniform transverse magnetic field. In the present note, we extend the analysis further to visco-elastic (Revin-Ericksen model) fluid.

### 2. Formulation of the Problem and Its Solution

Let  $u$  be the component of velocity in the direction of  $x$ -axis. A magnetic field of uniform strength  $H_0$  is applied in the direction of  $y$ -axis taken perpendicular to both the non-conducting parallel porous surfaces which are placed at  $y = \pm a$ . The fluid being injected through the surface  $y = -a$  and is being sucked through the surface  $y = a$  with uniform velocity  $V$ . The induced magnetic field may be neglected assuming that the conductivity of the fluid to be very small. All the parameters are independent of  $x$  except the pressure since the surfaces are infinite. The pressure gradient is assumed to oscillate in time in the direction of  $x$ -axis. The only non-zero component of velocity will be  $u(y,t)$ . The governing equation describing the flow of an incompressible visco-elastic conducting fluid in the presence of uniform transverse magnetic field is [2].

$$(1) \quad \frac{\partial u}{\partial t} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u}{\partial y^2} + \beta \frac{\partial^2}{\partial y^2} \left( \frac{\partial u}{\partial t} + v \frac{\partial u}{\partial y} \right) - \frac{\sigma}{\rho} B_0^2 u$$

where  $\nu$  is the kinematic viscosity,  $\beta$  the kinematic visco-elasticity,  $p$  the pressure,  $\rho$  the density of the fluid,  $\sigma$  the electrical conductivity and  $B_0 = \mu_e H_0$  (constant) the component of electromagnetic induction.

The boundary conditions are

$$(2) \quad u(a, t) = u(-a, t) = 0, \quad t > 0.$$

As in [1] the pressure gradient and the non-zero component of velocity are assumed to be of the form

$$(3) \quad \frac{\partial p}{\partial x} = \text{Re} [P_x \exp(int)]$$

and

$$(4) \quad u(y, t) = \text{Re} [w(y) \exp(int)],$$

where  $P_x$  is a constant, which represents the magnitude of pressure gradient oscillation.

Substituting (3) and (4) in (1) we get

$$(5) \quad \beta \lambda \frac{d^3 w}{dy^3} + (1 + \beta k^2) \frac{d^2 w}{dy^2} - \lambda \frac{dw}{dy} - (m + k^2)w = \frac{P_x}{\rho \nu},$$

$$\text{where } k^2 = \frac{in}{\nu}, \quad m = \frac{\sigma B_0^2}{\rho \nu}, \quad \lambda = \frac{\nu}{\nu}.$$

The corresponding boundary conditions are

$$(6) \quad w(a, t) = w(-a, t) = 0, \quad t > 0.$$

Since (5) is the differential equation of order three and we have only two boundary conditions, therefore we solve the equation regarding  $\beta$  as small. This is consistent with the derivation of Reelin-Ericksen constitutive equation where only small values of  $\beta$  is contemplated. Thus we set

$$(7) \quad w = w_0 + \beta w_1 + O(\beta^2).$$

Substituting (7) in (5) and equating the coefficients of different powers of  $\beta$ , we get

$$(8) \quad \frac{d^2 w_0}{dy^2} - \lambda \frac{dw_0}{dy} - (m + k^2)w_0 = \frac{P_x}{\rho \nu}$$

and

$$(9) \quad \frac{d^2 w_1}{dy^2} - \lambda \frac{dw_1}{dy} - (m + k^2)w_1 = -\lambda \frac{d^3 w_0}{dy^3} - k^2 \frac{d^2 w_0}{dy^2}.$$

The corresponding boundary conditions for  $w_0$  and  $w_1$  are

$$\begin{aligned} (10) \quad & w_0(a, t) = w_0(-a, t) = 0, \\ (11) \quad & w_1(a, t) = w_1(-a, t) = 0 \end{aligned} \quad \left. \vphantom{\begin{aligned} (10) \\ (11) \end{aligned}} \right\} \quad t > 0.$$

The solution of (8) subject to the condition (10) is

$$(12) \quad w_0(y) = \frac{P_x}{\rho \sqrt{(m+k^2)}} \left[ \exp\left(\frac{\lambda y}{2}\right) \left\{ \frac{\text{ch}\left(\frac{\lambda a}{2}\right)}{\text{ch } Ba} \text{ch } By - \frac{\text{sh}\left(\frac{\lambda a}{2}\right)}{\text{sh } Ba} \text{sh } By \right\} - 1 \right],$$

$$\text{where } B = \sqrt{\frac{\lambda^2}{4} + m + k^2}.$$

Substituting the value of  $w_0(y)$  in (9) we get

$$(13) \quad \frac{d^2 w_1}{dy^2} - \frac{dw_1}{dy} - (m+k^2)w_1 = \frac{P_x}{\rho \sqrt{(m+k^2)}} - \exp\left(\frac{\lambda y}{2}\right) (M \text{ch } By + N \text{sh } By),$$

$$\text{where } m = -g \frac{\text{ch}\left(\frac{\lambda a}{2}\right)}{\text{ch } Ba} + h \frac{\text{sh}\left(\frac{\lambda a}{2}\right)}{\text{sh } Ba}, \quad N = -h \frac{\text{sh}\left(\frac{\lambda a}{2}\right)}{\text{ch } Ba} + g \frac{\text{sh}\left(\frac{\lambda a}{2}\right)}{\text{sh } Ba},$$

$$g = \frac{k^2 \lambda^2}{4} + k^2 B^2 + \frac{\lambda^4}{8} + 2\lambda^2 B^2, \quad h = k^2 \lambda + \frac{3\lambda^3 B}{4} + \lambda B^3.$$

The solution of (13) subject to the condition (11) is

$$\begin{aligned} w_1(y) = & \frac{P_x}{2 \rho \sqrt{(m+k^2)} B} - \exp\left(\frac{\lambda y}{2}\right) \left\{ (M \text{ch } By + N \text{sh } By)y \right. \\ & \left. - a \left( M \frac{\text{ch } Ba}{\text{sh } Ba} \text{sh } By + N \frac{\text{sh } Ba}{\text{ch } Ba} \text{ch } By \right) \right\}. \end{aligned}$$

Thus the solution for  $u(y, t)$  is

$$\begin{aligned} (14) \quad u(y, t) = & \text{Re} \left\langle \left\{ w_0(y) + \beta w_1(y) \right\} \exp(i \int \dots) \right\rangle \\ = & \text{Re} \left\langle \frac{P_x}{\rho \sqrt{(m+k^2)}} \left[ \exp\left(\frac{\lambda y}{2}\right) \left\{ \frac{\text{ch}\left(\frac{\lambda a}{2}\right)}{\text{ch } Ba} \text{ch } By - \frac{\text{sh}\left(\frac{\lambda a}{2}\right)}{\text{sh } Ba} \text{sh } By \right\} - 1 \right] \right. \\ & + \frac{\beta}{2B} (M \text{ch } By + N \text{sh } By)y - \left( M \frac{\text{ch } Ba}{\text{sh } Ba} \text{sh } By + N \frac{\text{sh } Ba}{\text{ch } Ba} \text{ch } By \right) a \left. \right\rangle \exp(i \int \dots). \end{aligned}$$



It is evident from the above result that the velocity oscillates with the same frequency as the pressure gradient but that a phase lag, which depends on  $y$  exists. Thus the motion of the fluid which is adjacent to the boundaries will have a time wise phase shift relative to the motion near the centre line of the boundaries. The amplitude of the motion near the boundaries will differ from that near the centre line and in order to satisfy this condition, the amplitude will still approach zero as the boundaries are approached.

For  $\lambda \neq 0$ ,  $\beta = 0$  and  $m \neq 0$  we get

$$u(y,t) = \text{Re} \left\langle \frac{P_x}{\rho \nu (m+k^2)} \left[ \exp \left( \frac{\lambda y}{2} \right) \left\{ \frac{\text{ch}(\frac{\lambda a}{2})}{\text{ch } Ba} \text{ch } By - \frac{\text{sh}(\frac{\lambda a}{2})}{\text{sh } Ba} \text{sh } By \right\} - 1 \right] \exp(i\omega t) \right\rangle,$$

which is the solution for hydromagnetic pulsating flow of viscous incompressible fluid between parallel porous surfaces [5].

For  $\lambda = 0$ ,  $\beta = 0$  and  $m \neq 0$  we get

$$u(y,t) = \text{Re} \left\langle \frac{P_x}{\rho \nu (m+k^2)} \left[ \frac{\text{ch} \sqrt{(m+k^2)} y}{\text{ch} \sqrt{(m+k^2)} a} - 1 \right] \exp(i\omega t) \right\rangle,$$

which is the solution for hydromagnetic pulsating flow of viscous incompressible fluid between parallel surfaces [3].

For  $\lambda \neq 0$ ,  $\beta \neq 0$  and  $m = 0$  we get

$$u(y,t) = \text{Re} \left\langle \frac{P_x}{\rho \nu k^2} \left[ \exp \left( \frac{\lambda y}{2} \right) \left\{ \frac{\text{ch}(\frac{\lambda a}{2})}{\text{ch} \sqrt{(\frac{\lambda^2}{4} + k^2)} a} \text{ch} \sqrt{(\frac{\lambda^2}{4} + k^2)} y - \frac{\text{sh}(\frac{\lambda a}{2})}{\text{sh} \sqrt{(\frac{\lambda^2}{4} + k^2)} a} \text{sh} \sqrt{(\frac{\lambda^2}{4} + k^2)} y \right\} - 1 \right] \exp(i\omega t) \right\rangle,$$

which is the solution for the pulsating flow of viscous incompressible fluid between parallel porous surfaces

For  $\lambda = 0$ ,  $\beta = 0$  and  $m = 0$  we get

$$u(y,t) = \text{Re} \left\langle \frac{P_x}{\rho \nu k^2} \left( \frac{\text{ch } ky}{\text{ch } ka} - 1 \right) \exp(i\omega t) \right\rangle,$$

which is the solution for the pulsating flow of viscous incompressible fluid between parallel surfaces [1].

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# On the Growth of a Function Analytic in the Unit Disc

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Let  $f(z) = \sum_{n=0}^{\infty} a_n z^{\lambda_n}$  be analytic in the unit disc  $D = \{z : |z| < 1\}$ ,  $\lambda_0 = 0$  and  $\{\lambda_n\}_{n=1}^{\infty}$  is a strictly increasing sequence of natural numbers such that no element of the sequence  $\{a_n\}_{n=1}^{\infty}$  is zero. Set

$$M(r) = \max_{|z|=r} |f(z)|, \quad \mu(r) = \max_{n \geq 0} \left\{ |a_n| r^{\lambda_n} \right\}$$

and

$$\nu(r) = \max \left\{ \lambda_n : \mu(r) = |a_n| r^{\lambda_n} \right\}.$$

$M(r)$ ,  $\mu(r)$  and  $\nu(r)$  are called, respectively, the maximum modulus, the maximum term and the rank of the maximum term of  $f(z)$  for  $|z| = r$ . It is known ([3]) that,

$$(1) \quad \log \mu(r) = \log \mu(r_0) + \int_{r_0}^r (\nu(t)/t) dt, \quad r_0 < r < 1,$$

if  $\mu(r)$  and  $\nu(r)$  are unbounded functions of  $r$ .

Let  $f(z)$  be analytic in  $D$  with  $M(r) \rightarrow \infty$  as  $r \rightarrow 1$ . Set

$$\rho(q) = \limsup_{r \rightarrow 1} \frac{\log_q M(r)}{-\log(1-r)}$$

$$\lambda(q) = \liminf_{r \rightarrow 1} \frac{\log_q M(r)}{-\log(1-r)}$$

where  $\log_1 x = \log x$  and  $\log_q x = \log(\log_{q-1} x)$  for  $q \geq 2$ . If  $\rho(q) < \infty$  and  $\rho(q-1) = \infty$ ,  $q = 2, 3, \dots$ , then  $f(z)$  is said to be of index  $q$ . Further  $\rho(q)$  and  $\lambda(q)$  are called, respectively, q-order and lower q-order of  $f(z)$  (see [2]).

A coefficient characterisation of  $\rho(q)$  was recently obtained by Kapoor and Gopal ([2, Theorem 1]). Further, if  $\rho(q) > 0$ , then they have also obtained a coefficient characterisation of  $\lambda(q)$  ([2, Theorem 2]) for those functions which satisfy the condition

$$(2) \quad \Lambda(q) + \lambda(q) = \liminf_{r \rightarrow 1} \frac{\log_{q-1} \nu(r)}{-\log(1-r)}.$$

Here  $\Lambda(q) = 1$  if  $q = 2$ , otherwise  $\Lambda(q) = 0$ . It is known [1] that there exist functions analytic in  $D$  having index 2 with  $P(2) > 0$  and for which (2) does not hold for  $q = 2$ .

In the present note we prove.

Theorem: Let  $f(z)$  be analytic in  $D$ , having index  $q$ ,  $q \geq 3$ ,  $q$ -order  $P(q)$  ( $> 0$ ) and lower  $q$ -order  $\lambda(q)$ . Then,

$$\lambda(q) = \liminf_{r \rightarrow 1} \frac{\log_{q-1} \nu(r)}{-\log(1-r)}.$$

Our theorem shows that, for  $q \geq 3$ , the above condition (2) in Theorems 2 and 3 of [2] is redundant.

Proof of the theorem. It is known [2, Lemma 1] that

$$(3) \quad \lambda(q) = \liminf_{r \rightarrow 1} \frac{\log_q \mu(r)}{-\log(1-r)}$$

Now, since  $P(q) > 0$ , using (1) we have

$$\log \mu(r) < \log \mu(r_0) + \nu(r) \log(r/r_0)$$

$$< k \nu(r)$$

$k$  is a constant. This easily gives that

$$(4) \quad \liminf_{r \rightarrow 1} \frac{\log_q \mu(r)}{-\log(1-r)} \leq \liminf_{r \rightarrow 1} \frac{\log_{q-1} \nu(r)}{-\log(1-r)}$$

On the other hand, again by (1), we have

$$\begin{aligned} \nu(r) ((1-r)/2) &\leq \nu(r) \log [ (r+(1-r)/2) / r ] \\ &\leq \int_r^{r+(1-r)/2} (\nu(t)/t) dt \\ &\leq \log \mu(r+(1-r)/2) \end{aligned}$$

or

$$\log_{q-1} \nu(r) \leq \log_q \mu(r+(1-r)/2) + \log_{q-1} (2/(1-r))$$

for all  $r$  sufficiently near to 1. Now,  $r+(1-r)/2 \rightarrow 1$  as  $r \rightarrow 1$  and  $\log(1/(1-r)) \sim -\log(1-(r+(1-r)/2))$  as  $r \rightarrow 1$ . Thus, dividing the above inequality by  $-\log(1-r)$  and passing to limits we get

$$(5) \quad \liminf_{r \rightarrow 1} \frac{\log_{q-1} \nu(r)}{-\log(1-r)} \leq \liminf_{r \rightarrow 1} \frac{\log_q \mu(r)}{-\log(1-r)}$$

Proof of the theorem is complete in view of (3), (4) and (5).

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## The Distribution of Population Growth Rate in Nepal

Dr. Mrigendra Lal Singh

### 1. Background

The population of Nepal which was 5.6 millions in 1911 and which had remained virtually constant during the period of 1911-1930, started to show the growth trend only after 1930. The annual growth rate which was only 1.3%\* during 1930-1941 has increased to 2.1%\*\* by 1971-1981. This has resulted in a population of 14.1 millions for Nepal in 1981.

Though the recent observed rate is explosive\*\*\* and is likely to double Nepal's population in next 30 years, yet, it is far behind the expected rate of 2.4% for developing countries during 1980-1985; recorded rate of 2.4% in India for 1981 and 2.5% in Nepal as indicated by mid-term census taken in 1976.

Due to this fact, many demographers in Nepal are doubting the authenticity of the rate. But their doubts have yet not been substantiated or rebutted.

A review of intercensus growth rates so far observed in Nepal shows that, since 1930, it has been increasing slowly and steadily. Also, it shows that the reported rate for 1981 is the second highest next only to those (2.2%) for 1941-1952/54. The growth rates reported for the periods prior to 1961 are not of intrinsic values, for they have not been adjusted to equal census periods.

The population growth rates of Nepal adjusted to equal census periods are shown in Table 1.

Table 1  
(Adjusted Population growth rates based on equal census periods Nepal, 1911-1981)

Period	Growth rate	In %	
		Prior	Growth rate
1911-1921	0.35	1951-1961	2.03
1921-1931	0.35	1961-1971	2.07
1931-1941	0.35	1971-1981	2.10*

Source: Singh, M.L., "Population Dynamics of Nepal" Ph.D. thesis, Tribhuvan University, 1978, p. 22.

\*Press report released by CBS.

\* Estimated from Nepal population figures for 1930 and 1941.

\*\* Figures obtained from press report released by CBS.

\*\*\*Bogue has classified the population by different categories of growth rates. According to him, a population with growth rate of 2% and higher is explosive. See Bogue, D.J., 'Principles of Demography' John Willey and Sons, New York, 1969, p. 36.

The table clearly shows that the present growth rate of 2.1% is highest of all intercensus growth rates.

In this context, some few relevant questions arise. They are:

- a. Whether the present reported rate of 2.1% is reasonable or not?
- b. What is maximum growth rate that is possible for Nepal?
- c. What are the confidence limits of the variation of population growth rate in Nepal?

Though theoretically it can be proved that growth rate can have value as high as 10%, but in practice, a population with growth rate as high as 4% is hardly known.<sup>2</sup> Keeping in view of above fact, attempts are made in this paper to answer above questions.

For this, population growth rate matrix i.e.  $r$ -matrix is first constructed and from the matrix so constructed, confidential limits for growth rate ' $r$ ' are estimated and accordingly answers are obtained.

## 2. $r$ -matrix and probabilities of growth rates

In case of a closed population, the growth rate ' $r$ ' is estimated as the differences between the CBR ' $b$ ' and CDR ' $d$ '. Due to invariacy of Age structure of Nepal's population, the population of Nepal can be considered a closed one. Therefore, ignoring the effects of migration, the growth rate is estimated as  $r = b - d$ .

Since ' $b$ ' and ' $d$ ' are non-negative numbers, the minimum values of ' $b$ ' and ' $d$ ' that can be expected are zero's. On the assumption that ' $b$ ' is never less than ' $d$ ' for Nepalese population, the minimum value of ' $r$ ' becomes zero. The population with above values of vital rates is the stationary population. Therefore, keeping in view of existing high IMR (140 per thousand) in Nepal, the minimum values for ' $b$ ' and ' $d$ ' are taken as 15\* per thousand. Of course the maximum possible values for them are 50 per thousand.\*\*

The  $r$ -matrix, where,  $r = b - d$  is constructed for  $50 \geq b \geq 15$  ;  $50 \geq d \geq 15$  by dividing the range of variation of values of ' $b$ ' and ' $d$ ' into equal class intervals of width. The matrix so constructed is shown in Table 2.

\* Due to high proportion of young population (40% in the age group 0-14 years in Nepal), it may be argued that the CDR may go down as low as 4%. But at present, due to high FMR, such a drastic fall is not expected.

\*\*CBR and CDR higher than 50 lead a population whose life expectancy is less than 20 years and such population ultimately terminates.

Table 2  
(A hypothetical r-matrix)

Death rate in thousand	Birth rate in thousand							
	50	45	40	35	30	25	20	15
50	0							
45	5	0						
40	10	5	0					
35	15	10	5	0				
30	20	15	10	5	0			
25	25	20	15	10	5	0		
20	30	25	20	15	10	5	0	
15	35	30	25	20	15	10	5	0

The matrix shows the maximum possible value of 'r' in Nepal, when the population is closed, as 35 per thousand or 3.5%.

Assuming that b, d and 'r' take the discrete values as specified in the table, it is found that there are eight states at which 'r' becomes zero i.e. the population attains the stationary character. Therefore, it can be deduced that the probability of 'r' becoming 0% i.e.  $P(r=0\%)$  equals to 0.22. Also by using other sample points of the matrix, it can be shown that  $P(r=x)$  decreases as x increases. In fact, it is found that  $P(r=2.5\%)$  equals to 0.083 and  $P(r=3\%)$  equals to 0.027%. The above findings show that the probabilities of getting higher values of 'r' is very small.

### 3. Distribution function for 'r'

One of the statistical tool to express the character of a parameter is the distribution function. Therefore, the distribution for 'r' is derived in the following way:

Let u = upper limit of 'b' and 'd' i.e. 50 per thousand  
v = lower limit of 'b' and 'd' i.e. 15 per thousand

$$\frac{u-v}{h} = k, \text{ where } h = \text{width of the class interval} \\ k = \text{number of class intervals.}$$

Then  $P(r)$  values are estimated as:

$$f(hx) = \frac{(k-x)}{\sum k}, \text{ where } x=0, 1, 2, \dots, 7 \\ \therefore f(r) = \frac{(k - \frac{r}{h})}{\sum k} = \frac{2(hk-r)}{hk(k+1)}$$

$$\text{Now } hk = u-v = 50-15 = 35$$

$$\therefore f(r) = \frac{2(35-r)}{35(k+1)} \quad 0 \leq r \leq 35$$

$$\begin{aligned} \therefore \int f(r) dr &= \frac{2}{35(k+1)} \int (35-r) dr \quad (1) \\ &= \frac{35}{k+1} \end{aligned}$$

$f(r)$  becomes distribution function if  $\int f(r) dr = 1$

$$\text{i.e. } \frac{35}{k+1} = 1 \text{ or } k=34$$

$$\therefore f(r) = \frac{2}{35^2} (35-r), \quad 0 \leq r \leq 35 \quad (2)$$

$$\frac{u-v}{h} = k$$

$$\begin{aligned} P(R=hx) &= \frac{2(k-x)}{k(k+1)}, \quad x = 0, 1, 2, \dots, k \\ &= \frac{2(hk-hx)}{hk(k+1)} \end{aligned}$$

$$\therefore P(R=r) = \frac{2(hk-r)}{hk(k+1)}, \quad r = 0, h, 2h, \dots, kh$$

Let  $k \rightarrow \infty$ , keeping  $kh = 35$ ,

then probability that  $R$  assumes values in an interval of small length  $h$  around  $r$ , is

$$\begin{aligned} f_R(r) h &= \frac{2(35-r)}{35(35+h)} h \\ &\approx \frac{2(35-r)}{(35)^2}, \quad 0 \leq r \leq 35 \end{aligned}$$

An alternative derivation of  $f(r)$  is given below, which does not limit the value of  $k$  to 34, and which makes for nearly continuous.

Additions to be made to explain the facts shown in my paper

Estimation of  $E(r)$  and  $Var(r)$  in discrete case

From the matrix shown above,

The  $P(r)$  is found as  $P(r) = \frac{(k-x)}{\sum_{k=8}^7}$  where,  $x=0,1,2,\dots, 7$   
 $k=8$

$$\therefore E(r) = r P(r)$$

$$= 0 \cdot \frac{8}{\sum 8} + 5 \cdot \frac{7}{\sum 8} + 10 \cdot \frac{6}{\sum 8} + \dots + 35 \cdot \frac{1}{\sum 8}$$

$$= 11.666 \text{ per thousand or } 1.16\%$$

$$E(r^2) = r^2 P(r)$$

$$= 5^2 \cdot \frac{7}{\sum 8} + 10^2 \cdot \frac{6}{\sum 8} + \dots + 35^2 \cdot \frac{1}{\sum 8}$$

$$= 233.33$$

$$\therefore \text{Var}(r) = E(r^2) - [E(r)]^2 = 97.223$$

$$\therefore s_r = + \sqrt{\text{Var}(r)} = 9.86 \text{ per thousand}$$

Distribution function of 'r'

Suppose  $\frac{V-U}{h} = k$  where  $V =$  Maximum value of  $b$  or  $d$   
 $U =$  Minimum value of  $b$  or  $d$   
 $h =$  Width of the class interval  
 $k =$  Number of class intervals

$$\text{Then } f(hx) = \frac{(k-x)}{\sum k}$$

$$\text{so that } f(r) = \frac{k - \frac{r}{h}}{\sum k} = \frac{2(hk-r)}{hk(k+1)}$$

Since, in reality,  $b$ ,  $d$  and  $r$  are continuous variable, the probability function derived above is special case where  $b$  and  $d$  were supposed to take only discrete values such as 50, 45 etc.

Now extending to the continuous case,

$$f(r) = \frac{2(35-r)}{35(k+1)}, \quad 0 \leq r \leq 35, \quad hk = V-U = 35$$

$$\therefore f(r) = \frac{2}{35(k+1)} \int_0^{35} (35-r) \, dr$$



$$= \frac{2}{35(k+1)} \left[ (35r)^{35}_0 - \left(\frac{r^2}{2}\right)^{35}_0 \right]$$

$$= \frac{2.612.5}{35(k+1)} = \frac{35}{k+1}$$

Now  $f(r)$  becomes distribution function only if  $f(r) = 1$

$$\text{i.e. } \frac{35}{k+1} = 1$$

$$\therefore k+1 = 35 \text{ or } k=34$$

(Note that: in discrete case as shown in the matrix  $k=8$ ).

$\therefore$  The distribution function of 'r' is found as

$$f(r) = \frac{2}{35^2} (35-r) \quad 0 \leq r \leq 35$$

$$\therefore E(r) = \int r \, dr = 11.66 \text{ per thousand} = 1.16$$

$$\text{Var}(r) = E(r^2) - E(r)^2 = 97.32.$$

The values of  $E(r)$  and  $\text{Var}(r)$  estimated were found to be exactly the same as in case of the discrete case.

The expression (2) is derived distribution function of 'r' for Nepal.

This function is used to find the  $E(r)$  and  $\text{Var}(r)$

$$\text{Mean } (r) = E(r) = \int r \, dr \quad 0 \leq r \leq 35 \quad (3)$$

$$= \frac{2}{35^2} \int_0^{35} r(35-r) \, dr = 1.166\%$$

The result shows that mean value of the growth rate in Nepal is 1.17%.

Similarly by using the relation,

$$E(r^2) = \int r^2 f(r) \, dr \quad (4)$$

and

$$\text{Var}(r) = E(r^2) - [E(r)]^2 \text{ and } s_r = + \sqrt{\text{Var}(r)} \quad (5)$$

the standard error of estimation of mean is estimated as 9.86 per thousand i.e. 0.98%.

#### 4. Confidence limits for 'r'

For simplicity the confidence limits for the variation of 'r' are defined as:

$$E(r) \pm s_r^* \quad (6)$$

∴ The limits for the variation of 'r' are obtained as 2.15% and 0.18%.

A glance at the values of the growth rate 'r' estimated<sup>3</sup> and observed so far in Nepal shows that except for two or three values, most of the values lie within the limits found above.

#### 5. Conclusion

Since the reported population growth rate of Nepal for 1981 is found to be uppermost limit of the confidence limits found in the present study, it is concluded that there is no ground to suspect the validity of present value. As regards maximum possible value of 'r', it is found that 7 in 10 chances (68%), the observed value of population growth rate is likely to fluctuate between 0.18% and 2.15%. The conclusions are however not conclusive, for, once the magnitude of migration comes to vital role in Nepal's population phenomenon, the picture will be entirely different.

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## A Type of Semi-ring

Prahlad Singh & N.S. Yadav

### Introduction

This paper investigates a generalization of a ring, to be called R-semi-ring and explores certain properties thereof.

### 1. Definitions

An R-semi-ring is a system  $R$  with two operations, multiplication and commutative addition  $(+)$  with the following properties:

- (i)  $(a+b)+c = a+(b+c)$ ,  $a, b, c \in R$  ;
- (ii)  $a(b+c) = ab+ac$ ,  $a, b, c \in R$  ;
- (iii) There exists an element  $0$  (zero) in  $R$  such that

$$0+a = a, a \in R$$

and (iv)  $0a = 0$ ,  $a \in R$ .

If multiplication is commutative,  $R$  is commutative and if it is associative,  $R$  is an associative R-semi-ring. If there is an element  $1$  in  $R$  such that  $1a = a1 = a$ ,  $a \in R$ , then  $R$  is an R-semi-ring with unity  $1$ .

Hereinafter we shall use simply semi-ring for R-semi-ring.

### 2. Theorem

Every abelian semi-group  $G$  with identity is the additive semi-group of some semi-ring.

### Proof

We can presuppose that the semi-group operation of  $G$  is written additively. If  $a, b \in G$ , let us define  $ab = 0$ . That all the properties of a semi-ring are satisfied is evident. This zero-semi-ring is obviously commutative-associative.

It can be seen that in the semi-ring  $R$  defined here,  $a^2 = 0$  and  $ab = -ba$ ,  $a, b \in R$ . If  $R$  does not consist of zero alone, then  $R$  is a semi-ring without unity.

### 3. Definitions

Regular element: An element  $a$  in an associative semi-ring  $R$  is regular if there exists an element  $x \in R$  such that  $a \times a = a$ .

A non-empty subset  $S$  of  $R$  will be called regular if each element of  $S$  is regular.

#### 4. Theorem

If  $R$  be (associative) regular, then for each non-zero element  $a \in R$ , there exists an idempotent  $b$  such that  $aR = bR$ . Conversely, if  $R$  be associative with unity such that for each non-zero element  $a$  of  $R$  there is an idempotent  $b$  such that  $aR = bR$ , then  $R$  is regular.

Proof: Let  $R$  be regular and  $a$  a non-zero element of  $R$ . Then there exists an element  $x$  of  $R$  such that  $axa = a$ . Since  $(ax)(ax) = (axa)x = ax$ , it follows that  $ax$  is an idempotent.

We shall now show that  $(ax)R = aR$ .

Let  $(ax)r \in (ax)R$ . Hence  $axr = a(xr) \in aR$ . If  $ar \in aR$ , then  $axar \in aR$ .

But,  $(ax)(ar) \in axR$ .

Conversely, let  $a$  be any non-zero element of  $R$  and let  $b$  be an idempotent such that  $aR = bR$ .

Thus  $b = ax$  for some  $x \in R$ .

Since  $a \in bR$ ,  $a = by$  for some  $y \in R$ .

Now  $a = by = b^2y = b(by) = ba$  and hence  $axa = (ax)a = ba = a$ .

#### 5. Definition

An element  $b$  of a semi-ring  $R$  is called nilpotent if and only if there exists a positive integer  $n$  such that  $b^n = 0$ . A subset  $B (\subseteq R)$  is called nil if every element of  $R$  is nilpotent.

#### 6. Theorem

An (associative) regular semi-ring with unity contains no non-zero nil subset  $B$  such that  $BR \subseteq B$ .

#### Proof

Let  $b$  be a non-zero element of  $B$  with  $BR \subseteq B$ . Then, by Theorem 4, there exists an idempotent  $c$  such that  $cR = bR$ . Hence  $c = bx$  for some  $x$  in  $R$ , that is,  $c \in B$ , a contradiction.

#### 7. Definition

If  $a$  and  $b$  are non-zero elements of a semi-ring  $R$  with  $ab = 0$  or  $ba = 0$ , then  $a$  and  $b$  are called zero divisors of  $R$ .

8. Theorem

Let  $R$  be (associative) regular with unity with no zero-divisors. If the additive structure of  $R$  is that of a group, then the non-zero elements of  $R$  form a multiplicative group.

Proof

Let  $a$  be a non-zero element of  $R$ . Then there exists an element  $x \in R$  such that  $axa = a$ , i.e.  $a(xa-1) = 0$ ; but  $a \neq 0$ . Hence  $xa = 1$ .

Similarly  $xyx = x$  for some  $y \in R$  i.e.  $yx = 1$ . Now,  $ax = (yx)(ax) = y(xa)x = yx = 1$ ; that is  $a$  has a multiplicative inverse  $x$ .

Remark

If  $R$  is commutative, then it is a field.

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## On Certain Sets in Pasch Geometric Modules of Dimension Three

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The concept of a Pasch Geometry is given in [1] or [3] and that of geometric module in [2]. Geometric modules over geometric Sfields give rise to projective spaces. In this short paper, we prove two basic propositions on the cardinality of certain subsets which are technical in proving results on geometric modules of dimension three.

Suppose  $V$  is a geometric module over a geometric Sfield  $A$ , the dimension of  $V$  over  $A$  being 3 [2]. Since  $A^* = A - \{0\}$  acts on  $V$ , we consider the geometry  $V/A^*$  [2]. For  $v \in V$ ,  $\bar{v}$  denotes the element of  $V/A^*$ . Since  $v^{\pi} = 1^{\pi}v$ , we have  $\bar{v}^{\pi} = \bar{v}$ . Also, let  $(\bar{v}, \bar{v}, \bar{w}) \in \Delta_{V/A^*}$ . Then  $\exists \alpha, \beta \in A^*$  such that  $(v, \alpha v, \beta w) \in \Delta_V$ . Suppose  $\beta w \neq 0$ . Then  $\beta w \in Sp(v) \Rightarrow \beta w = \gamma v$  for some  $\gamma \in A$ ,  $\gamma \neq 0$ . So  $\bar{w} = \bar{v}$ . Hence  $V/A^*$  as a geometry is projective [1]. Since  $\dim_A V$  is 3, it is easy to see that  $\dim V/A^*$  is also 3. So  $V/A^*$  corresponds naturally to a projective space of projective dimension two i.e. a projective plane.

In this paper  $V$  will be a geometric module over a geometric Sfield  $A$  with dimension  $V$  equal to 3.

### 1.1 Definition

- (i) For  $\alpha \in A^*$ , let  $C_\alpha = \{ \beta : (\alpha, \alpha^{\pi}, \beta) \in \Delta_A \}$ .
- (ii) For  $v_1, v_2 \in V$ ,  $v_1, v_2$  independent, and  $\alpha \in A^*$ , we set

$$L_\alpha(v_1, v_2) = \{ u : u \in V, (u, v_1, \alpha v_2) \in \Delta_V \}.$$

Note that  $L_\alpha(v_1, v_2) \neq \emptyset$ . We fix the elements  $v_1, v_2$ , and write  $L_\alpha$  for  $L_\alpha(v_1, v_2) \forall \alpha \in A^*$ . For any set  $S$ ,  $\text{card}(S)$  will denote the cardinality of the set  $S$ .

### 1.2 Proposition

- (i)  $\text{Card}(C_\alpha) = \text{Card}(C_\beta) \forall \alpha, \beta \in A^*$ .
- (ii)  $\text{Card}(C_\alpha) \leq \text{Card}(L_\alpha) \forall \alpha \in A^*$ .

Proof

- (i) We note that  $\gamma \in C_\alpha$  if and only if  $(\alpha, \alpha^*, \gamma) \in \Delta_A$  if and only if  $(\beta, \beta^*, \beta\alpha^{-1}\gamma) \in \Delta_A$  i.e.  $\beta\alpha^{-1}\gamma \in C_\beta$ . Now the association  $\gamma \leftrightarrow \beta\alpha^{-1}\gamma$  is clearly a bijective mapping.
- (ii) Choose  $u_0 \in V$  such that  $(u_0, v_1, \alpha v_2) \in \Delta_V$ . Let  $\gamma \in C_\alpha$ ,  $\gamma \neq 0$ . Then
- $$(\alpha, \alpha^*, \gamma) \in \Delta_A \Rightarrow (1, 1^*, \alpha^{-1}\gamma) \in \Delta_A \Rightarrow (v_1, v_1^*, \alpha^{-1}\gamma v_1) \in \Delta_V$$
- So  $(v_1, \alpha v_2, u_0), (v_1, v_1^*, \alpha^{-1}\gamma v_1) \in \Delta_V$   
 $\Rightarrow \exists u \in V$  such that  $(u, v_1, \alpha v_2), (u, \alpha^{-1}\gamma v_1, u_0^*) \in \Delta_V$ .

Note that  $u \in L_\alpha$ . Thus give  $\gamma \in C_\alpha$ ,  $\gamma \neq 0$ ,  $\exists u \in L$  such that  $(u, \alpha^{-1}\gamma v_1, u_0^*) \in \Delta_V$ .

Note that since  $v_1, u_0$  are independent,  $u_0 \neq u$ . Let  $\phi(\gamma) = \{u \in L_\alpha : (u, \alpha^{-1}\gamma v_1, u_0^*) \in \Delta_V\}$

So  $\phi(\gamma) \neq \text{null set}$ . Let  $\phi(0) = \{u_0\}$ . Suppose  $u \in \phi(\gamma_1) \cap \phi(\gamma_2)$ . Then  $(u, \alpha^{-1}\gamma_1 v_1, u_0^*), (u, \alpha^{-1}\gamma_2 v_1, u_0^*) \in \Delta_V$ . Since  $v_1, u_0$  are independent, we get  $\alpha^{-1}\gamma_1 = \alpha^{-1}\gamma_2$  i.e.  $\gamma_1 = \gamma_2$ . Thus,

$$\phi: C_\alpha \rightarrow \text{Set of subsets of } L_\alpha$$

is a map such that  $\phi(\gamma_1)$  and  $\phi(\gamma_2)$  are disjoint for  $\gamma_1 \neq \gamma_2$ . Clearly this defines, using axiom of choice, an injective mapping from  $C_\alpha$  to  $L_\alpha$ .

1.3 Proposition

$$\text{Card}(L_\alpha) = \text{Card}(L_\beta) \quad \forall \alpha, \beta \in A^*.$$

Proof

Let  $v_3 \in V^*$ ,  $v_3 \notin \text{Sp}(v_1, v_2)$ . Note that such  $v_3$  exists, since  $\dim V$  is greater than 2. Let  $w_0 \in V$  such that  $(w_0, v_1, \beta\alpha v_3^*) \in \Delta_V$ . Note  $w_0 \notin \text{Sp}(v_1, v_2)$ , since otherwise  $\beta\alpha v_3^*$  and hence  $v_3$  would be in  $\text{Sp}(v_1, v_2)$  as  $\alpha \neq 0$ ,  $\beta \neq 0$ . We define a map

$$\phi_{(w_0)}: L_\beta(v_1, v_2) = L_\beta \rightarrow L_\alpha(v_2, v_3)$$

as follows: Let  $u \in L_\beta$  so that  $(u, v_1, \beta v_2) \in \Delta_V$ . Then  $(v_1, w_0, \beta \alpha v_3)$ ,  $(v_1, u, \beta v_2) \in \Delta_V \Rightarrow \exists s \in V$  such that  $(s, u^\#, w_0), (s, \beta v_2, \beta \alpha v_3) \in \Delta_V$  i.e.  $\beta^{-1}s \in L_\alpha(v_2, v_3)$ . We set  $\phi_{(w_0)}(u) = \beta^{-1}s \in L_\alpha(v_2, v_3)$  where  $(s, u^\#, w_0) \in \Delta_V$ .

$\phi_{(w_0)}$  is well defined: Suppose also  $\beta^{-1}t \in L_\alpha(v_2, v_3)$  such that  $(t, u^\#, w_0) \in \Delta_V$ . Then  $s, t \in \text{Sp}(u, w_0) \cap \text{Sp}(v_2, v_3)$ . Note  $u \notin \text{Sp}(v_2, v_3)$ , otherwise since  $u, v_2$  are independent,  $v_3$  would be in  $\text{Sp}(u, v_2) = \text{Sp}(v_1, v_2)$ . So  $\text{Sp}(u, w_0) \cap \text{Sp}(v_2, v_3)$  has dimension at most one. So  $\exists \delta \in A^*$  with  $t = \delta s$ . But then  $(\delta s, u^\#, w_0), (s, u^\#, w_0) \in \Delta_V$ . But  $u, w_0$  are independent, so  $\delta = 1$  and  $t = s$ .

$\phi_{(w_0)}$  is one-one: Let  $(\phi_{(w_0)}(u_1) = \phi_{(w_0)}(u_2) = \beta^{-1}s$  so that  $\beta^{-1}s \in L_\alpha(v_2, v_3)$  and  $(s, u_1^\#, w_0), (s, u_2^\#, w_0) \in \Delta$ . The  $\exists x \in V$  such that  $(x, u_2, u_1^\#), (x, w_0, w_0^\#) \in \Delta$ . So  $s = \gamma w_0$ ,  $\gamma \in A$ . If  $\gamma \neq 0$ , then  $\gamma w_0$  and so  $w_0$  would be in  $\text{Sp}(u_1, u_2) \subseteq \text{Sp}(v_1, v_2)$ , a contradiction. So  $\gamma = 0$  i.e.  $x = 0$  and so  $u_1 = u_2$ .

Thus  $\phi_{(w_0)}$  is an injection from  $L_\beta$  into  $L_\alpha(v_2, v_3)$ . Note that since  $v_1 \notin \text{Sp}(v_2, v_3)$ , the symmetry implies there is an injection from  $L_\alpha(v_2, v_3)$  to  $L_\beta$ . So by Bernstein-Schoder theorem,  $\text{Card}(L_\beta) = \text{Card}(L_\alpha(v_2, v_3))$ . Taking  $\alpha = \beta$ ,  $\text{Card}(L_\alpha) = \text{Card}(L_\alpha(v_2, v_3)) = \text{Card}(L_\beta)$ . This completes the proof.

#### Remark

If  $A$  is sharp (i.e. naturally a skewfield), then  $C_\alpha = \{0\} \forall \alpha \in A$  if and only if  $C_1 = \{0\}$ . Also, if  $C_1 = \{0\}$ , then  $A$  is sharp, so  $V$  is sharp and hence  $\text{Card}(L_\alpha) = 1 \forall \alpha \in A$ . Conversely, if  $\text{Card}(L_1) = 1$ , then  $C_1 = \{0\}$  so  $V$  is sharp.

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## A Class of Generating Functions

R.M. Shrestha

### Abstract

A new class of generating functions of the form

$$(1-t)^{-a} H[-4m^2 t]^m x(1-t)^{-2m} J = \sum_{n=0}^{\infty} g_{n,m}^a(x) t^n$$

is used to obtain known and new generating functions.

### 1. Introduction

Various extensions of the generating function [3]

$$(1.1) \quad (1-t)^{-1} {}_2F_1 \left[ \begin{matrix} -S, 1 \\ p \end{matrix}; -4x(1-t)^{-2} \right] \\ = \sum_{n=0}^{\infty} {}_3F_2 \left( \begin{matrix} -n, n+1, S \\ 1, p \end{matrix}; x \right) t^n$$

where

$$(1.2) \quad {}_3F_2 \left( \begin{matrix} -n, n+1, S \\ 1, p \end{matrix}; x \right) = R_n(x)$$

is the Rice polynomial [4].

Brafman's extension of (1.1) is of the form [5]

$$(1.3) \quad (1-t)^{-1} {}_pF_q \left[ \begin{matrix} (a_p) \\ (b_q) \end{matrix}; -4xt(1-t)^{-2} \right] \\ = \sum_{n=0}^{\infty} {}_{p+2}F_{q+2} \left[ \begin{matrix} -n, n+1, (a_p) \\ 1, 1, (b_q) \end{matrix}; x \right] t^n,$$

where  $(a_p)$  stands for the sequence of parameters  $a_1, a_2, \dots, a_p$ .

Further extensions in the forms

$$(1.4) \quad (1-t)^{-1} H[-4xt(1-t)^{-2}] J = \sum_{n=0}^{\infty} g_n(x) t^n,$$

and

$$(1.5) \quad (1-t)^{-1} H[-4m^2 t]^m x(1-t)^{-2m} J = \sum_{n=0}^{\infty} g_{n,m}(x) t^n,$$



where

$$(1.6) \quad H(x) = \sum_{n=0}^{\infty} a_n x^n,$$

$$(1.7) \quad g_n(x) = \sum_{k=0}^{\infty} \frac{(-n)_k (1+n)_k}{(1)_k k!} a_k x^k,$$

and

$$(1.8) \quad g_{n,m}(x) = \sum_{k=0}^{\lfloor n/m \rfloor} \frac{(-n)_{mk} (1+n)_{mk}}{(1)_{2mk}} a_k \lfloor (2m)^{2m} x \rfloor^k,$$

were furnished by Fasenmeyer [2] and Shrestha [5] respectively.

In the present paper, we give an elementary extension covering all the above extensions and indicate how we obtain known and new generating functions. Since our method of proof is classical, we just give a short outline of the proof.

## 2. Main result

If

$$(2.1) \quad H(x) = \sum_{n=0}^{\infty} a_n x^n,$$

and

$$(2.2) \quad g_{n,m}^{\alpha}(x) = \sum_{k=0}^{\lfloor n/m \rfloor} \frac{(-n)_{mk} (\alpha)_n (\alpha+n)_{mk}}{(\alpha)_{2mk} n!} a_k \lfloor (2m)^{2m} x \rfloor^k,$$

then

$$(2.3) \quad (1-t)^{-\alpha} H \lfloor (-4m^2 t)^m x (1-t)^{-2m} \rfloor = \sum_{n=0}^{\infty} g_{n,m}^{\alpha}(x) t^n,$$

where  $m$  is a non-zero positive integer.

Proof. Use (2.1) in the left-side of (2.3) and simplify with the help of

$$(2.4) \quad \sum_{n=0}^{\infty} \sum_{k=0}^{\lfloor n/m \rfloor} A(n-mk, k) = \sum_{k=0}^{\infty} \sum_{n=0}^{\infty} A(n, k),$$

$$(2.5) \quad (a)_m (a+m)_n = (a)_{m+n},$$

$$(2.6) \quad (a)_{mk} = m^{mk} \left(\frac{a}{m}\right)_k \left(\frac{a+1}{m}\right)_k \dots \left(\frac{a+m-1}{m}\right)_k, \quad m > 0, \quad k \geq 0$$

and

$$(2.7) \quad (-n)_k = (-1)^k n! / (n-k)!, \quad 0 \leq k \leq n,$$

to find

$$\begin{aligned} (1-t)^{-\alpha} {}_H\mathcal{L}(-4m^2t)^m x(1-t)^{-2m} &= \sum_{k=0}^{\infty} \frac{(-4m^2t)^{mk} a_k x^k}{(1-t)^{\alpha+2mk}} \\ &= \sum_{k=0}^{\infty} \sum_{n=0}^{\infty} \frac{(-4m^2)^{km} (\alpha+2mk)_n a_k}{n!} x^k t^{n+mk} \\ &= \sum_{n=0}^{\infty} \sum_{k=0}^{[n/m]} \frac{(-n)_{mk} (\alpha)_n (\alpha+n)_{mk}}{(\alpha)_{2mk} n!} a_k [(2m)^{2m} x]^k t^n \\ &= \sum_{n=0}^{\infty} g_{n,m}^{\alpha}(x) t^n. \end{aligned}$$

In particular, when  $\alpha = 1$ , we arrive at the result (1.6) due to Shrestha [5]. Results due to Sister Celine follows from (1.6) by taking  $m = 1$ . The other results due to Rice and Brafmann may be obtained similarly.

### 3. Applications

As a first application of (2.3), we derive the following generating function [6]

$$(3.1) \quad \sum_{n=0}^{\infty} \frac{(2\lambda)_n \Gamma(\lambda + \frac{1}{2})}{n!} R_n^*(x) t^n = (1-t)^{-2} {}_2F_1^* \left[ \begin{matrix} \lambda, a \\ c \end{matrix}; -\frac{4xt}{(1-t)^2} \right]$$

$$\text{where } {}_2F_1^* \left( \lambda, a; c; -\frac{4xt}{(1-t)^2} \right) = \frac{1}{\Gamma(c)} {}_2F_1 \left( \lambda, a; c; -\frac{4xt}{(1-t)^2} \right),$$

and

$$(3.2) \quad R_n^*(x) = {}_3F_2^*(-n, n+2\lambda, a; \lambda + \frac{1}{2}, c; x)$$

denotes the hypergeometric polynomial appearing as coefficients appearing in the expansion of the confluent hypergeometric function in series of Bessel functions. Further properties of  $R_n^*(x)$  can be found in Shrestha [6].

In order to obtain (3.1), we take  $m = 1$ ,  $\alpha = 2$  and

$$(3.3) \quad H\left[\frac{4xt}{(1-t)^2}\right] = {}_2F_1^*(\lambda, a; c; -\frac{4xt}{(1-t)^2})$$

in (2.3).

As a second example, we have the following interesting generating function

$$(3.4) \quad (1-t)^{-\alpha} {}_pF_q \left[ \begin{matrix} (a_p); (b_q); (-4m^2t)^m \end{matrix} ; x(1-t)^{-2m} \right] \\ = \sum_{n=0}^{\infty} {}_{p+2m+1}F_{q+2m} \left[ \begin{matrix} \Delta(m; -n), \Delta(m; \alpha+n), \alpha, (a_p) \\ \Delta(2m; \alpha), (b_q) \end{matrix} ; x \right] t^n$$

where  $\Delta(m; a)$  stands for the sequence of parameters

$$\frac{a}{m}, \frac{a+1}{m}, \dots, \frac{a+m-1}{m}, m \text{ being a positive integer.}$$

This result is obtained from (2.3) by taking

$$(3.5) \quad H(u) = {}_pF_q \left[ \begin{matrix} (a_p); (b_q) \end{matrix} ; u \right].$$

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## An Iteration of the $M_{k,m}$ -Transform

S.R. Pant

### Abstract

In this paper we deal with the iteration of the well-known  $M_{k,m}$ -Transform. As Stieltjes Transform is obtained by the first iteration of the Laplace Transform, by iterating its generalisation, we expect a generalised Stieltjes Transform.

### 1. Introduction

If the determining function of the Laplace Transform

$$(1.1) \quad f(s) = \int_0^{\infty} e^{-st} \phi(x) dt \quad (s > 0)$$

is itself the Laplace Transform of another function, say  $\alpha(x)$ , that is, if

$$(1.2) \quad \phi(t) = \int_0^{\infty} e^{-xt} \alpha(x) dx,$$

then

$$(1.3) \quad f(s) = \int_0^{\infty} \frac{\alpha(x)}{s+x} dx,$$

which is known as the Stieltjes Transform [4]. In this note, we shall obtain the first iteration of the  $M_{k,m}$ -Transform

$$(1.4) \quad f(s) = \int_0^{\infty} e^{-\lambda st} (st)^{-m-\frac{1}{2}} M_{k,m}(st) \phi(t) dt,$$

where  $\lambda$  is a real positive parameter greater than  $\frac{1}{2}$ ,  $k$  &  $m$  may be real or complex and  $2m \neq -1, -2, -3, \dots$ . This transform was given by the author [3]. This transform is still true for  $\lambda = \frac{1}{2}$  when

$$|t^{+k-m-\frac{1}{2}} \phi(t)| \in L(0, \infty)$$

It reduces to (1.1) for  $\lambda = 3/2$  and  $k + m = \frac{1}{2}$ .

### 2. Iteration

In this section we obtain the generalisation of the Stieltjes transform by iteration of the  $M_{k,m}$ -Transform.

Theorem. If

$$(2.1) \quad f(s) = \int_0^{\infty} e^{-\lambda sx} (sx)^{-m-\frac{1}{2}} M_{k,m}(sx) \phi(x) dx$$

where

$$(2.2) \quad \phi(x) = \int_0^{\infty} e^{-\lambda' xt} (xt)^{-m'-\frac{1}{2}} M_{k',m'}(xt) \mathcal{A}(t) dt,$$

then

$$(2.3) \quad f(s) = \int_0^{\infty} \mathcal{L}(\lambda + \frac{1}{2})s + (\lambda' + \frac{1}{2})t \mathcal{J}^{-1}$$

$$F_2 \left[ \begin{matrix} 1, m-k-\frac{1}{2}, m'-k'-\frac{1}{2}, 2m+1 \\ 2m+1, 2m'+1 \end{matrix} ; \frac{s}{(\lambda + \frac{1}{2})s + (\lambda' + \frac{1}{2})t}, \frac{t}{(\lambda + \frac{1}{2})s + (\lambda' + \frac{1}{2})t} \right] \mathcal{A}(t) dt$$

provided that

- a)  $2m$  and  $2m'$  are not negative integers,
- b)  $\lambda, \lambda' > \frac{1}{2}, s > 0$
- c)  $\mathcal{A}(t) = O(t^{\mu}), \mu > 0$ , for  $t \rightarrow 0$   
 $= O(e^{-\gamma t}), \gamma > 0$ , for  $t \rightarrow \infty$ ,

and  $F_2$  standing for the hypergeometric function of two variables.

Proof. On substituting from (2.2) in (2.1), we get

$$\begin{aligned} f(s) &= s^{-m-\frac{1}{2}} \int_0^{\infty} e^{-\lambda sx} x^{-m-\frac{1}{2}} M_{k,m}(sx) \left\{ \int_0^{\infty} e^{-\lambda' xt} (xt)^{-m'-\frac{1}{2}} M_{k',m'}(xt) \right. \\ &\quad \left. \mathcal{A}(t) dt \right\} dx \\ &= s^{-m-\frac{1}{2}} \int_0^{\infty} \frac{\mathcal{A}(t) dt}{t^{m'+\frac{1}{2}}} \int_0^{\infty} e^{-(\lambda s + \lambda' t)x} x^{-m-m'-1} M_{k,m}(sx) M_{k',m'}(t) dx, \end{aligned}$$

provided that the change of order of integration is permissible.

Now, evaluating the inner integral with the help of the result [3]

$$(2.4) \quad \int_0^{\infty} e^{-pt} t^{q-1} M_{k,m-\frac{1}{2}}(at) M_{k',m'-\frac{1}{2}}(bt) dt$$



$$= a^m b^{m'} \Gamma(p+\frac{1}{2}(a+b))^{-q-m-m'} \Gamma(q+m+m') F_2 \left[ \begin{matrix} q+m+m', m-k, m'-k' \\ 2m, 2m' \end{matrix}; \frac{a}{p+\frac{1}{2}(a+b)}, \frac{b}{p+\frac{1}{2}(a+b)} \right]$$

provided that  $(q + m + m') > 0$ ,  $(p + \frac{1}{2}a + \frac{1}{2}b) > 0$ ,

we arrive at the required result.

As regards the validity of the change of order of integration, the t-integral and the x-integral are absolutely convergent under the conditions stated in the theorem. Moreover the resulting integral is also convergent under the same conditions. Hence the change of order of integration is permissible.

Corollary. If  $\lambda = \lambda' = 3/2$ , and  $k = m + \frac{1}{2}$ ,  $k' = m' + \frac{1}{2}$ , the  $F_2$  in (2.3) reduces to

$$F_2 = \frac{2(s+t)}{s+2t} {}_1F_0 \left[ 1; -; \frac{t}{s+2t} \right] = 2.$$

Hence (2.3) reduces to the well-known Stieltjes transform obtained by the iteration of (1.1).

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## Integrals Involving Generalised Struve's Function

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### Abstract

The object of the present paper is to give a new generalisation of Struve's function and evaluate some integrals involving the generalised Struve's function.

### 1. Introduction

Struve's function  $H_{\nu}(z)$  of order  $\nu$  is defined by [1]

$$\begin{aligned} (1.1) \quad H_{\nu}(z) &= \frac{2(\frac{1}{2}z)^{\nu}}{\Gamma(\frac{1}{2})\Gamma(\nu+\frac{1}{2})} \int_0^1 (1-t^2)^{\nu-\frac{1}{2}} \sin zt \, dt \\ &= \frac{2(\frac{1}{2}z)^{\nu}}{\Gamma(\frac{1}{2})\Gamma(\nu+\frac{1}{2})} \int_0^{\frac{1}{2}\pi} \sin^{2\nu}\theta \sin(z \cos \theta) \, d\theta, \operatorname{Re}(\nu+\frac{1}{2}) > 0 \\ &= \sum_{r=0}^{\infty} \frac{(-1)^r (\frac{1}{2}z)^{\nu+2r+1}}{\Gamma(r+3/2)\Gamma(\nu+r+3/2)}, \text{ for all values of } \nu. \end{aligned}$$

In the year 1962, Bhowmick defined the generalised Struve's function  $H_{\nu}^{\lambda}(z)$  by the formula [2]

$$(1.2) \quad H_{\nu}^{\lambda}(z) = \sum_{r=0}^{\infty} \frac{(-1)^r (\frac{1}{2}z)^{\nu+2r+1}}{\Gamma(r+3/2)\Gamma(\nu+\lambda r+3/2)}, \quad (\lambda > 0).$$

We now consider a new generalisation of Struve's function  $H_{\nu}^{\lambda,k}(z)$  defined by

$$(1.3) \quad H_{\nu}^{\lambda,k}(z) = \sum_{r=0}^{\infty} \frac{(-1)^r (\frac{1}{2}z)^{\nu+2r+1}}{\Gamma(kr+3/2)\Gamma(\nu+\lambda r+3/2)}, \quad k > 0, \lambda > 0.$$

### 2. Finite Integral Representations

We now express the generalised Struve's function as integrals involving another generalised Struve's function and also as integrals involving generalised hypergeometric function.

$$(2.1) \quad H_{\nu+\rho+1}^{\lambda,k}(z) = \frac{z^{\rho+1}}{2^{\rho}\Gamma(\rho+1)} \int_0^{\frac{1}{2}\pi} \sin^{(\nu+1)(2-\lambda)}\theta \cos^{2\rho+1}\theta H_{\nu}^{\lambda,k}(z \sin^{\lambda}\theta) (z \sin^{\lambda}\theta) \, d\theta.$$

Proof. We have

$$\begin{aligned}
 & \frac{z^{\rho+1}}{2^{\rho} \Gamma(\rho+1)} \int_0^{\frac{1}{2}\pi} \sin^{(\nu+1)(2-\lambda)} \theta \cos^{2\rho+1} \theta H_{\nu}^{\lambda,k}(z \sin^{\lambda} \theta) d\theta \\
 &= \frac{z^{\rho+1}}{2^{\rho} \Gamma(\rho+1)} \int_0^{\frac{1}{2}\pi} \sin^{(\nu+1)(2-\lambda)} \theta \cos^{2\rho+1} \theta \sum_{r=0}^{\infty} \frac{(-1)^r \left(\frac{1}{2} z \sin^{\lambda} \theta\right)^{\nu+2r+1}}{\Gamma(kr+3/2) \Gamma(\nu+\lambda r+3/2)} d\theta \\
 &= \sum_{r=0}^{\infty} \frac{(-1)^r 2 \left(\frac{1}{2} z\right)^{\nu+\rho+1+2r+1}}{\Gamma(\rho+1) \Gamma(kr+3/2) \Gamma(\nu+\lambda r+3/2)} \int_0^{\frac{1}{2}\pi} \sin^{2(\nu+\lambda r+1)} \theta \cos^{2\rho+1} \theta d\theta \\
 &= \sum_{r=0}^{\infty} \frac{(-1)^r 2 \left(\frac{1}{2} z\right)^{\nu+\rho+1+2r+1}}{\Gamma(\rho+1) \Gamma(kr+3/2) \Gamma(\nu+\lambda r+3/2)} \frac{\Gamma(\nu+\lambda r+3/2) \Gamma(\rho+1)}{2 \Gamma(\nu+\lambda r+\rho+5/2)} \\
 &= H_{\nu+\rho+1}^{\lambda,k}(z), \text{ which is the required result.}
 \end{aligned}$$

The term by term integration in the above simplification is justified because of the fact that the series is uniformly convergent in  $0 \leq \theta \leq \frac{1}{2}\pi$ , and this infinite series is multiplied by an absolutely integrable function, and then integrated term by term.

In particular, if  $k = 1$ , we get the known result due to Bhowmick [2]. Two other interesting results derivable from (2.1) are

$$(2.2) \quad H_{\nu}^{\lambda,k}(z) = \frac{z^{\nu+\frac{1}{2}}}{2^{\nu-\frac{1}{2}} \Gamma(\nu+\frac{1}{2})} \int_0^{\frac{1}{2}\pi} \sin^{1-\frac{1}{2}\lambda} \theta \cos^{2\nu} \theta H_{-\frac{1}{2}}^{\lambda,k}(z \sin^{\lambda} \theta) d\theta$$

where  $\operatorname{Re}(\nu+3/2) > 0$ ,

and

$$(2.3) \quad H_{\nu+\rho+1}^{\lambda,k}(z) = \frac{z^{\rho+\frac{1}{2}}}{2^{\rho} \Gamma(\rho+\frac{1}{2})} \int_0^1 x^{(\nu+1)(2-\lambda)} (1-x^2)^{\rho} H_{\nu}^{\lambda,k}(zx^{\lambda}) dx,$$

where  $\operatorname{Re}(\nu+3/2) > 0$ ,  $\operatorname{Re}(\rho+1) > 0$ .

The result follows from (2.1) by taking  $\nu = -\frac{1}{2}$  and replacing  $\rho + \frac{1}{2}$  by  $\nu$ ; and the result (2.3) follows similarly by putting  $\sin \theta = x$  in (2.1). Known results can be obtained by specialising the parameters in these results.

Representation II. For  $\operatorname{Re}(\nu+3/2) > 0$ ,  $k$  and  $\lambda$  are positive integers,

$$(2.4) \quad H_{\nu}^{\lambda, k}(z) = \frac{\Gamma(3/2k) (\frac{1}{2}z)^{\nu+1}}{\Gamma(3/2) \Gamma(3/2k-1) \Gamma(\nu+3/2)} \int_0^1 (1-t)^{3/2k-2} \cdot {}_0F_{\lambda+k-1} \left( -; \frac{5}{2k}, \dots, \frac{3+2k-2}{2k}, \frac{\nu}{\lambda} + \frac{3}{2\lambda}, \dots, \frac{\nu}{\lambda} + \frac{3+2\lambda-2}{2\lambda}, \frac{-z^2 t}{4\lambda^k k} \right) dt$$

Proof. Using  $\Gamma(a+k) = (a)_k \Gamma(a)$  and

$$(a)_{mk} = m^{mk} \left(\frac{a}{m}\right)_k \left(\frac{a+1}{m}\right)_k \dots \left(\frac{a+m-1}{m}\right)_k, \quad m > 0, \quad k \geq 0,$$

in (1.3), we arrive at

$$(2.5) \quad H_{\nu}^{\lambda, k}(z) = \frac{(\frac{1}{2}z)^{\nu+1}}{\Gamma(3/2) \Gamma(\nu+3/2)} {}_1F_{k+\lambda} \left( 1; 3/2k, \dots, (3+2k-2)/2k, \frac{\nu+3/2}{\lambda}, \frac{\nu+3/2+\lambda-1}{\lambda}; \frac{-z^2}{4\lambda^k k} \right).$$

It is easy to show that [4]

$$(2.6) \quad \frac{(1)_r}{(3/2k)_r} = \frac{\Gamma(3/2k)}{\Gamma(3/2k-1)} \cdot \frac{\Gamma(r+1) \Gamma(3/2k-1)}{\Gamma(3/2k+r)} \\ = \frac{\Gamma(3/2k)}{\Gamma(3/2k-1)} B(r+1, 3/2k-1) \\ = \frac{\Gamma(3/2k)}{\Gamma(3/2k-1)} \int_0^1 t^r (1-t)^{3/2k-2} dt.$$

The required result follows on using (2.6) in (2.5) and integrating term by term.

Two particular cases of special interest are as follows:

$$(2.7) \quad H_{\nu}^{\lambda}(z) = \frac{(\frac{1}{2}z)^{\nu+1}}{\Gamma(1) \Gamma(\nu+3/2)} \int_0^1 (1-t)^{-1/2} {}_0F_{\lambda} \left( -; \frac{2\lambda+3}{2\lambda}, \dots, \frac{2\nu+2\lambda+1}{2\lambda}; \frac{-z^2 t}{4\lambda^{\lambda}} \right) dt$$

and

$$(2.8) \quad H_{\nu}(z) = \frac{(\frac{1}{2}z)^{\nu+1}}{\Gamma(1) \Gamma(\nu+3/2)} \int_0^1 (1-t)^{-1/2} {}_0F_1 \left( -; \frac{2\nu+3}{2}; -z^2 t/4 \right) dt,$$

These results seem to be new. The first result is obtained from (2.4) by taking  $k=1$ , and the second follows from (2.7) by taking  $\lambda = 1$ .

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GLOSSARY OF MATHEMATICAL TERMS  
(Proposed)  
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Naive सरल, अकृत्रिम	Non-algebraic अबीजिय
Natural यथार्थ, स्वाभाविक, प्राकृतिक	Norm नर्म, मानक
Naught शून्य	Normal अभिलंब, लम्बरूप, यथाक्रम
Nautical नाविक, जहाजी, समुद्री	Nonmalization अभिलम्बिकरण
n-dimension एन-डाइमेन्सन्	Notation संकेत
Nebula नेबुला, नीहारिका	Nought शून्य, गणना, संख्या पद्धति
Negative ऋणात्मक, निषेधार्थक	Null शून्य
Negater निषेधक	Number संख्या, गणना
Negation निषेध	Numerable गणना योग्य
Neighbourhood सामिप्य, समीपता	Numeral अंक, संख्या चिन्ह
Neptune नेपच्यून, वरुण	Numerator अंश
Nest नेष्ट	Numerical संख्या-सूचक, संख्यात्मक
Neutral तटस्थ, उदासीन	Numerically संख्यानुसार
Nil शून्य	(0)
Nilpotent शून्यभावी	Object वस्तु
Nine नाँ	Oblate ध्रुवतीर च्याप्तो परेको, लघ्वृत्ता, वेष्टो
Ninefold नाँगुना	Oblique टेढो, वक्र, तैसो, फुकेको
Ninety नब्बे	Oblong आयताकार
Nineteen उन्नाइस	Observation निरूपणा, निरीक्षाण
Nineteenth उन्नाइसौ	Obtuse अधिक
Ninetieth नब्बेऔँ	Occurrence घटना
Ninth नवौँ	Octagon अष्टकोण, अष्टभुज
Nonagon नाँकोण, नाँभुज	Octagonal अष्टकोणिय, अष्टभुजीय
	Octahedral अष्ट फलकीय

यो शब्दाली त्रि.वि. कीर्तिपुर बहुमुखी क्याम्पस, गणित तथा नेपाली शिक्षाण समितिले संयुक्त रूपमा तयार गरिएको हो ।

Octahedron अष्टफलक

Octant अष्टांशक

Octuple आठगुना

Odd बिषम, विजोर

Omega ओमेगा, ( $\omega$ )

One एक

Open खुला, वितृत

Operand संकार्य

Operate संक्रिया

Operation संक्रिया

Operational संक्रियात्मक

Operative संकारी

Operator संकारक

Opposite विपरीत

Opposition वियुति

Optimal इष्टतम

Optimization इष्टतमीकरण

Optimizing इष्टतमीकरण

Optimum इष्टतम

Orbit कक्षा

Orbital अर्विटल

Order क्रम, कोटि, घात, मूलक, समूहक

Ordered क्रमित

Ordinal क्रमसूचक

Ordinarily साधारणतया

Ordinary साधारण, सामान्य

Ordinate कोटि

Orientability अभिविन्यसनीयता

Orientable अभिविन्यसनीय

Origin मूलविन्दु, उद्गम

Original मूल, प्रारम्भिक

Orthocentre लंबकेन्द्र

Orthocentric लंबकेन्द्रीय

Orthogonal लंबकोणाय, लांविक

Orthogonality लंबकोणायता, लांविक्ता

Orthogonalization लांविकीकरण

Orthogonally लांविकत

Orthonormal अर्थोनर्मल, लांविक

Oscillate दोलन गर्नु

Oscillating दोलायमान

Oscillation दोलन

Oscillator दोलित्र

Oscillatory दोलन, दोलनी

Oscillogram अस्सिलोग्राम

Osculating आश्लेषी

Osculation आश्लेषन, आश्लेषणी

Osculatory स्पर्शी

Osmotic परासरणी

Outer बाह्य

Oval अंडाकार

Ovaloid अंडवक्राम

Overlap अतिव्यापित, अतिव्यापन

Overstability अतिस्थायित्व	Partition विभाजन
Overstairs अतिप्रकल	Path पथ
(P)	Pattern प्रतिरूप
Pair जोड़ा, युग्म	Pedal पदिक, पाद
Paired युग्मित, युगलित	Pendulum दौलक
Pairing युग्मन	Penetrate वेधन
Parwise युगलतः	Pentagon पंचभुज
Parabola परवलय, अनुवृत्त	Per प्रति
Parabolic परवलिक, अनुवृत्तीय	Per cent प्रतिशत
Paraboloid पैराबोल्वाय्द्	Percentage प्रतिशतता
Paraboloidal पैराबोल्वाइडी	Percentile शततमक
Paracompact अनुसंहत	Perfect पूर्ण, परिपूर्ण
Paradox विरोधामास	Perihelion उपसौर
Parallax पैरेलैक्स	Perimeter परिमाप
Parallel समानान्तर	Period आवर्तकाल, अवधि
Parallelogram समानान्तर चतुर्भुज	Periodic आवर्ती
Parallelopiped समानान्तर षट्फलक	Periodical आवर्ती
Parameter प्राचल	Permanent स्थायी
Parametric प्राचालिक	Permanence स्थायीत्व
Parametrix प्राचालक	Permeable पारगम्य
Parenthesis सानोकोष्ठ ( )	Permute क्रमचय गर्नु
Part अंश, खण्ड, भाग	Permutation क्रमचय
Partial आंशिक	Perpendicular लंब
Partially अंशतः	Perpendicularity लम्बता
Particle कण	Perpendicularly लंबत, अनुलम्ब
Particular विशेष, विशिष्ट	Perpetual सतत, शाश्वत

Perturbation दाँम	Predecessor पूर्ववर्ती, पूर्वग
Perturbed दाँव्य	Predicted प्रागुक्त
Perturbing दाँमकारी	Prediction प्रागुक्ति
Phase कला, कोणांक	Prefix पूर्वलग्न
Phi फाई (φ)	Press चाप, चाप लगाउनु, दवाउनु
Physical भौतिक	Pressure चाप, दाब
Physics भौतिकशास्त्र	Price मूल्य
Pi पाई (π)	Primary प्राथमिक
Piece टुकड़ा, सण्ड	Prime अमाज्य, दृढ
Pitch पिच	Primitive खादि, जाय
Pivot धुराग्न, धुरी	Principal मूल, मुख्य
Plane समतल	Principle सिद्धान्त
Planet ग्रहट	Probability प्रायिकता, सम्भाव्यता
Planetary ग्रहीय	Probable संभाव्य
Plus धन	Problem समस्या
Point बिन्दु	Process प्रक्रम
Pointwise बिन्दुशः	Produce उत्पादन गर्नु
Polar ध्रुवीय	Product उत्पादय, गुणनफल
Pole ध्रुव	Progression श्रेणी
Polynomial बहुपद, बहुपदीय	Project प्रक्षेपन गर्नु
Population जनसंख्या	Projected प्रक्षिप्त, प्रक्षेपित
Position स्थान, स्थिति	Projectile प्रक्षेपि
Positive धनात्मक, धन	Projection प्रक्षेपण, प्रक्षेप
Positivity धनता	Proof प्रमाण, उपपत्ति
Postulate अभिगृहीत	Proper उचित
Power घात, सामर्थ्य, दामता	Proportion समानुपात

Proportional समानुपातिक

Pulley धिरनी

Proportionality समानुपातिकता

Pulsating स्पंदमान

Proportionate समानुपातिक

Pure शुद्ध

Proposition साध्य

Push कर्ष, धकेलाह

Prove प्रमाणित गर्नु

Pyramid पिरैमिड

Psi साइ ( $\psi$ )

Pull अमिकर्ष, अमिकर्षण